

PROCEDURAL MIXTURE SETS*

Rommewinkel, Hendrik^{1,2}

¹Hitotsubashi University, 2-1 Naka, Kunitachi, Tokyo 186-0004, hendrik.r@r.hit-u.ac.jp

²Waseda Institute for Advanced Study, 1-104 Totsukamachi, Shinjuku City, Tokyo 169-8050

THIS VERSION: AUGUST 2025

Abstract

The paper characterizes the Shannon (1948) and Tsallis (1988) entropies in a standard framework of decision theory, mixture sets. Procedural mixture sets are introduced as a variant of mixture sets in which it is not necessarily true that a mixture of two identical elements yields the same element. This allows the process of mixing itself to have an intrinsic value. The paper proves the surprising result that simply imposing the standard axioms of von Neumann-Morgenstern on preferences on a procedural mixture set yields the entropy as a representation of procedural value. An application of the theorem to decision processes and the relation between choice probabilities and decision times elucidates the difficulty of extending the drift-diffusion model to multi-alternative choice.

KEYWORDS: Decision theory, procedural value, decision processes, mixture sets, entropy, reduction of compound mixtures, decision times, associativity

*Jaffray Lecture at Risk, Uncertainty, and Decision 2024. Many thanks to participants at the Society for the Advancement of Economic Theory conference 2019 and Risk, Uncertainty, and Decision Conference 2024, seminar participants at Erasmus Universiteit Rotterdam and Waseda University and Chun-ting Chen, Soo Hong Chew, and Patrick DeJarnette for helpful comments.

1 INTRODUCTION

Economic theory frequently utilizes information measures.¹ The present paper characterizes the entropy information measures by Shannon (1948) and Tsallis (1988) in a simple algebraic framework. Concretely, we employ variations of the mixture sets and classical expected utility axioms of Herstein and Milnor (1953) and von Neumann and Morgenstern (1944).

In standard mixture sets, from the reduction of compound mixtures axiom and the independence axiom follows betweenness (Chew, 1989): if $a \succsim b$, then $a \succsim \mu a \oplus (1 - \mu)b \succsim b$. The entropy representation characterized in the present paper violates betweenness. This is natural since the entropy is a measure of statistical dispersion, not of average value. This leaves two avenues for characterization: changing the reduction of compound mixtures or the independence axiom. We focus on the former method and show that the result can be directly applied to the latter method.

In the first main result we change the reduction of compound mixtures axiom of mixture sets into an associativity condition. Associativity is a new axiom that states that the order of mixing does not matter but unlike reduction of compound mixtures allows for $\mu a \oplus (1 - \mu)a \not\succeq a$. We call sets that fulfill these assumptions procedural mixture sets because not only the result a matters, but also whether a mixture operation was performed or not. Surprisingly, the change from a mixture set to a procedural mixture set is all that is needed to obtain an entropy representation: in a procedural mixture set, the expected utility axioms — weak order, continuity, and independence characterize the Shannon and Tsallis entropies.

We apply our model of procedural value to axiomatic characterizations of decision times (Baldassi et al., 2020; Echenique & Saito, 2017; Fudenberg et al., 2020; Koida, 2017) in decision processes with multiple alternatives. We show that decision processes in which choice probabilities follow the Luce (1959) model of stochastic choice form a procedural mixture set. Consider a relation \succsim on decision processes with the interpretation of “takes as least as long as” which represents a procedural value (time) as opposed to a consequentialist value (utility). Betweenness is naturally

¹The entropy is used to model inequality (Shorrocks, 1980; Theil, 1967), segregation (Frankel & Volij, 2011), the utility of gambling (Luce et al., 2008a, 2008b), diversity (Nehring & Puppe, 2009), consumer demand (Theil, 1965), freedom of choice (Suppes, 1996), market concentration (Hennessy & Lapan, 2007; Herfindahl, 1950; Hirschman, 1980), and information costs (Caplin et al., 2017; Sims, 2003).

violated if choice is non-instantaneous because even the decision between two identical options may take some additional time. The weak order, continuity, and independence axioms naturally apply to this relation: in particular, the independence axiom can be understood as stating that decision times are increasing in the decision times of sub-decisions. The longer a sub-decision takes, the longer –*ceteris paribus*– the overall decision should take. Applying the main result to decision processes thus yields a testable empirical prediction: if for a decision domain the Luce (1959) model holds and decision times are a function of decision probabilities that is increasing in the decision times of subdecisions, then decision times can be represented by an entropy. Hick (1952) first suggested that decision durations can be modeled by the Shannon (1948) entropy and thus we call the resulting model of decision processes the Luce-Hick model, which we characterize axiomatically. We use this result to explain the well-known difficulty of finding multi-alternative extensions for the Diffusion Drift model Ratcliff (1978) and Ratcliff et al. (2016).

In the second main result we restrict the independence axiom to mixtures with disjoint support but maintain the mixture set assumptions introduced by Herstein and Milnor (1953). By embedding a procedural mixture set into the mixture set, we again obtain the Shannon and Tsallis entropy representation for a subset of the relation. We apply this result to nested stochastic choice (Kovach & Tserenjigmid, 2022). In nested stochastic choice Luce’s IIA axiom holds among subsets of alternatives. This allows us to generate Hick’s law type predictions for decision times when some pairs of alternatives are similar and others are dissimilar to each other.

The paper proceeds as follows. An introductory example highlights the main application to decision processes in Section 2. The axioms and the representation theorem for procedural mixtures are presented in Section 3. Section 4 provides comparative statics results and interprets the parameters of the model. Section 5 discusses the representation results that maintain reduction of compound mixtures but weaken independence. The relation to the literature is given in Section 6. Section 7 concludes.

2 INTRODUCTORY EXAMPLE

Suppose an analyst observes a sample of choices by a decision maker choosing between various items. This choice is not instantaneous; the deci-

sion maker undergoes some thought process until a decision is made. The duration of this thought process will generally depend on how difficult the decision is. The literature on decision processes (Bogacz et al., 2006; Usher et al., 2013) has established that the more uncertain ex ante the choice between two alternatives is, the longer a decision takes. Thus, when two alternatives are equally likely to be chosen, then the decision process takes longer than when one alternative is much more likely to be chosen than the other.² The drift diffusion model (Ratcliff, 1978) captures this basic empirical fact but there is no agreed-upon generalization to multiple options (Ratcliff et al., 2016). The generalization to multiple options is complicated by the presence of similarity, attraction, and compromise effects (Rieskamp et al., 2006; Roe et al., 2001) in stochastic choice. Generally, the availability of additional alternatives may influence the relative choice probabilities of two alternatives, complicating the extension of the relation between choice probabilities and decision times from two options to multiple options. However, as we will show in Section 3, in the absence of the aforementioned effects, it turns out that plausible assumptions lead to a very restrictive functional form for the relation between choice probabilities and decision times.

Consider the classical example of a decision maker who faces a choice between various methods of transportation to travel to another city. An analyst records the choice probabilities and decision times shown in Figure 1. On the left side, the table lists decision problems with choice probabilities and on the right side, decision times. We will call the combination of a decision problem (i.e., the list of available alternatives) and choice probabilities a *decision process*. From their decision times we can derive a weak order over decision processes. If a and b are decision processes, then $a \succsim b$ is interpreted as a takes at least as long as b . Such a relation will form the primitive of our model.

The listed decision processes exhibit two important features that motivate the formal model presented in the next section:

First, there are decision problems which list the same alternative more than once. For example, there is a trivial decision between taking a bus and taking a bus. Such a trivial decision may still involve a reaction time or may even induce the decision maker to engage in a search for differences between the two alternatives. Treating decision processes

²In the experimental literature, the decision time commonly refers to the average decision time of a sample of subjects and the choice probabilities refer to the relative frequency of choice.

Option 1	Option 2	Option 3	Duration
Airplane	BUS	CAR	1.9s
20%	20%	60%	
AIRPLANE	BUS	-	1.5s
50%	50%		
BUS	BUS	-	1.5s
50%	50%		
AIRPLANE	CAR	-	1.3s
25%	75%		
BUS	CAR	-	1.3s
25%	75%		
AIRPLANE	TRAIN	-	1.2s
20%	80%		
BUS	-	-	.5s
100%			
TRAIN	-	-	.5s
100%			

Figure 1: Choice Probability and Decision Time Data

simply as probability distributions over what alternative is chosen would conflate such a decision process with a process that involves no choice. We will later make this precise by defining that the decision processes in Figure 1 lack *reducibility*.

Second, the relative choice probabilities of two alternatives do not depend on other alternatives available: the airplane and bus are equally likely to be chosen when compared with each other and this does not change when the car is available. This property is an instance of the independence of irrelevant alternatives (IIA) axiom of Luce (1959). The probabilities of the three option decision problem in Figure 1 are such that conditioning on any subset yields the corresponding binary choice probabilities. Decisions can therefore be seen as composed of binary sub-decisions. The IIA axiom guarantees that the order in which we compose such binary sub-decisions does not matter. We will later make this precise by defining that the decision processes in Figure 1 fulfill *associativity*.

The above two observations motivate us to study *procedural mixtures* denoted by $\mu a \oplus (1 - \mu)b$ that fulfill associativity but, unlike standard mixture sets, do not fulfill reducibility. If a and b are decision processes from Figure 1, then $\mu a \oplus (1 - \mu)b$ is the decision process which assigns each option in a and b its original choice probability multiplied with μ and $1 - \mu$, respectively. Crucially, if a and b contain identical or repeated options, these are not reduced to a single instance with the probability being the sum. They remain separately listed as the decision maker may take additional time to discern between the two identical options.

For example, denoting by $[\text{BUS}]$ the trivial decision problem that only offers to ride the bus, we can denote by $1/2[\text{BUS}] \oplus 1/2[\text{BUS}]$ the decision problem in which the (of course, meaningless) choice between a bus and a bus is made. Importantly, unlike in mixture sets, $[\text{BUS}] \neq 1/2[\text{BUS}] \oplus 1/2[\text{BUS}]$ as required by our first observation. The choice between the airplane, the bus, and the car can be written as $1/5[\text{AIRPLANE}] \oplus 4/5(1/4[\text{BUS}] \oplus 3/4[\text{CAR}])$ but also as $2/5(1/2[\text{AIRPLANE}] \oplus 1/2[\text{BUS}]) \oplus 3/5[\text{CAR}]$. Thus, every decision process can be written as an arbitrary composition of binary subdecisions. Luce’s IIA axiom guarantees that the mixture weights correspond to the true choice probabilities of the subdecision problems and that our decision processes can consistently be disaggregated into binary choices. This corresponds to our second observation discussed above.

The procedural mixture notation allows us to write a decision process in terms of its *sub-decision processes*. For example, $(1/4[\text{BUS}] \oplus 3/4[\text{CAR}])$ is a sub-decision process of $1/5[\text{AIRPLANE}] \oplus 4/5(1/4[\text{BUS}] \oplus 3/4[\text{CAR}])$. In Figure 1 we observe that the decision time of a choice process is increasing in the decision time of any sub-decision process. For example, the decision process between the airplane, bus and the car takes longer than the decision process between the airplane and the train just as the decision between the bus and the car takes longer than being assigned the train with certainty. This corresponds to the independence axiom (Herstein & Milnor, 1953; von Neumann & Morgenstern, 1944), being applied to a procedural mixture set. According to the independence axiom, $[\text{AIRPLANE}] \succsim [\text{BUS}]$, i.e., $[\text{AIRPLANE}]$ takes at least as long as $[\text{BUS}]$, if and only if $1/2[\text{AIRPLANE}] \oplus 1/2[\text{CAR}] \succsim 1/2[\text{BUS}] \oplus 1/2[\text{CAR}]$. In Section 3 we show that this assumption (together with continuity of the relation on a rich³ set of decision probabilities) allows us to characterize a sharp

³Technically, the result requires arbitrary decision probabilities to be available for all

functional form for the average decision time; the Tsallis and Shannon entropies of the choice probabilities.

It is often perceived as a weakness of the Luce model that adding an (almost) identical option to a decision increases the (combined) probability of that option (e.g., Debreu, 1960). This is because all alternatives are treated symmetrically and the qualitative differences do not matter. Analogously, in our model, the (meaningless) decision between two buses takes as much time as the decision between an airplane and a bus. We address this issue with a second set of results in Section 5 where we allow for the decision between the two buses and the decision between a bus and an airplane to be treated differently and show that in a mixture set, a suitably weakening of the independence axiom yields the same representation.

3 PROCEDURAL MIXTURES

For ease of comparison, we first recapitulate the axioms of Herstein and Milnor (1953) which for a mixture set $\langle \mathcal{M}, \oplus \rangle$ where \oplus is a mixture operator $\oplus : \mathcal{S} \times \mathcal{S} \times [0, 1] \rightarrow \mathcal{S}$ are given as follows:

$$1a \oplus (1 - 1)b = a, \quad (1)$$

$$\mu a \oplus (1 - \mu)b = (1 - \mu)b \oplus \mu a, \quad (2)$$

$$\lambda[\mu a \oplus (1 - \mu)b] \oplus (1 - \lambda)b = (\lambda\mu)a \oplus (1 - \lambda\mu)b \quad (3)$$

where each axiom holds for all $a, b \in \mathcal{M}$ and all $\mu, \lambda \in [0, 1]$. We may call these axioms, respectively, connectedness, commutativity, and reduction of compound mixtures. λ and μ are the mixture weights. In the context of our example, these are probabilities and we will use these terms interchangeably. An element a is called an *outcome* if there do not exist distinct b and c such that $a = \mu b \oplus (1 - \mu)c$ for some $\mu \in (0, 1)$.

The reduction of compound mixtures axiom is implied⁴ by two economically distinct properties, associativity,

$$\begin{aligned} & (1 - \lambda)\left[\frac{\mu}{1 - \lambda}a \oplus \frac{1 - \lambda - \mu}{1 - \lambda}b\right] \oplus \lambda c \\ &= \mu a \oplus (1 - \mu)\left[\frac{1 - \lambda - \mu}{1 - \mu}b \oplus \frac{\lambda}{1 - \mu}c\right] \end{aligned} \quad (4)$$

alternatives to fulfill richness. In practice, sufficiently fine probabilities can be generated from quality variations, probabilities of actually receiving an item, etc..

⁴Notably, associativity is not implied by reduction of compound mixtures as Example 1 in Mongin (2001) shows.

and reducibility:

$$\mu a \oplus (1 - \mu)a = a. \quad (5)$$

for all $a, b \in \mathcal{M}$ and all $\mu \in [0, 1]$ and $\lambda \in [0, 1]$. Associativity states that the order of mixing does not matter. Reducibility expresses that the mixing itself is irrelevant.

Example. The classical example of a mixture set is a set of lotteries on a set of alternatives \mathcal{X} . These can be formalized as $\Delta X \equiv \{p : \mathcal{X} \rightarrow [0, 1] \mid \sum_{x \in \mathcal{X}} p(x) = 1\}$ with a mixture operation fulfilling $(\alpha p \oplus (1 - \alpha)q)(x) = \alpha p(x) + (1 - \alpha)q(x)$ for all $x \in \mathcal{X}$. Notice that in our example, a decision process in which a decision maker chooses bus with probability $1/2$ or another bus is not the same as the trivial decision process in which the decision maker does not make a choice and receives a bus with certainty. Lotteries and mixture sets would not reflect this since $\frac{1}{2}b \oplus \frac{1}{2}b = b$. In procedural mixture sets we therefore remove the reducibility axiom to allow the procedural mixture set to distinguish between the decision process involving a choice, $\frac{1}{2}b \oplus \frac{1}{2}b$ and the trivial decision process involving no choice, b . Thus, the mixture operation $\mu a \oplus (1 - \mu)b$ means in this context that the decision maker makes a time-consuming decision with probabilities μ and $1 - \mu$ between alternatives a and b and that this decision is time-consuming even if the alternatives are effectively identical. \square

Fishburn (1982) generalized mixture sets by replacing the identity = with an equivalence relation in the mixture axioms. We now remove the axiom of reducibility and perform a generalization analogous to Fishburn (1982).

Definition 1 (Procedural Mixture Set). A procedural mixture set $\langle \mathcal{S}, \oplus, \approx \rangle$ is a set \mathcal{S} endowed with a mixture operator $\oplus : \mathcal{S} \times \mathcal{S} \times [0, 1] \rightarrow \mathcal{S}$ and an equivalence relation \approx which fulfills for all $a, b, c \in \mathcal{S}$ and all $\mu \in [0, 1]$, $\lambda \in [0, 1]$:

$$1a \oplus (1 - 1)b \approx a, \quad (6)$$

$$\mu a \oplus (1 - \mu)b \approx (1 - \mu)b \oplus \mu a, \quad (7)$$

$$\begin{aligned} (1 - \lambda) \left[\frac{\mu}{1 - \lambda} a \oplus \frac{1 - \lambda - \mu}{1 - \lambda} b \right] \oplus \lambda c \\ \approx \mu a \oplus (1 - \mu) \left[\frac{1 - \lambda - \mu}{1 - \mu} b \oplus \frac{\lambda}{1 - \mu} c \right] \end{aligned} \quad (8)$$

Connectedness and commutativity remain unchanged. Reduction of compound mixtures is replaced by associativity.

Example. The data structure consisting of entries in the form of rows in Figure 1 is a procedural mixture set given our assumptions about choice probabilities and equivalent decision times discussed in Section 2. To see this, we now specify the set \mathcal{S} , the operation \oplus , the equivalence relation \approx , and the resulting equivalence classes \mathcal{S}/\approx .

Let \mathcal{X} be a set of outcomes. A decision process with n outcomes is an element of $\mathcal{S}_n \equiv \mathcal{X}^n \times \Delta\{1, \dots, n\}$, i.e., a list of n (possibly identical) outcomes and a probability distribution over the n outcomes. Denote an element of \mathcal{S}_n by $(x_1, p_1; \dots; x_n, p_n)$. Let $\mathcal{S} = \bigcup_{n=1}^{\infty} \mathcal{S}_n$. We define the operator \oplus as follows:

$$\mu a \oplus (1 - \mu)b = \begin{cases} a, & \mu = 1 \\ b, & \mu = 0 \\ (x_1^a, \mu p_1^a; \dots; x_{n^a}^a, \mu p_{n^a}^a; x_1^b, (1 - \mu)p_1^b; \dots; x_{n^b}^b), & \text{else.} \end{cases} \quad (9)$$

We further define the equivalence relation \approx such that $a \approx b$ if b can be obtained from a by removing or adding any number of zero probability outcomes and permuting the combinations of outcomes and probabilities.

The crucial difference to a standard lottery space is that whenever two outcomes appear more than once in the decision process, these are not treated as the same outcome with the probability being the sum of the two times they appear. \square

We are interested in binary relations on procedural mixture sets. A function $U : \mathcal{S} \rightarrow \mathbb{R}$ is called a *representation* of \succsim if $a \succsim b$ if and only if $U(a) \geq U(b)$. In particular, we are interested in the following representation of binary relations on procedural mixture sets.

Definition 2 (Mixture Entropy). A binary relation \succsim on \mathcal{S} is a mixture entropy value if there exists a function $U : \mathcal{S} \rightarrow \mathbb{R}$ called a mixture entropy and parameters $q \in \mathbb{R}, r \in \mathbb{R}_{++}$ such that U represents \succsim and for all $a, b \in \mathcal{S}$ and $\mu \in [0, 1]$,

$$U(\mu a \oplus (1 - \mu)b) = \mu^r U(a) + (1 - \mu)^r U(b) + q \cdot H_r(\mu) \\ H_r(\mu) = \begin{cases} -\mu \ln \mu - (1 - \mu) \ln(1 - \mu), & r = 1 \\ \frac{1 - \mu^r - (1 - \mu)^r}{r - 1}. & r \neq 1 \end{cases} \quad (10)$$

where $0 \ln 0 \equiv 0$ here and thereafter.

Example. If \succsim represents the decision times, then the decision times must be a monotone transformation T of the representation U . For simplicity, assume for the moment that T is the identity function, i.e., $T(u) = u$.⁵ For such a linear T , the parameters that lead to the decision times in Figure 1 are characterized as follows: First, each trivial decision (where only one option is available) takes a reaction time of 0.5 seconds. This can be seen as the non-decision component of a response time (Luce, 1986). Second, the most difficult binary decision (in which the choice probabilities are equal) takes 1.5 seconds. Let the deliberation time of this decision process be the decision time minus the reaction time, i.e. 1 second. Third, given any decision process, if we replace every final option by repeating the exact same decision process, then the deliberation time doubles. For example, four options that are equally likely to be chosen take twice the deliberation time, i.e., 2 seconds, as two equally likely options. These assumptions together determine the parameters of the mixture entropy value as $r = 1$ and $k = 1/\ln 2$. In the remainder of this section, we provide a set of simple axioms that characterize when the decision times are an increasing transformation of (10). \square

Let \succsim be a relation on a procedural mixture set \mathcal{S} . We use the symbols \sim and \succ to denote the symmetric and asymmetric parts of \succsim . We assume the following classical axioms:

Axiom 1 (Weak Order). \succsim is complete and transitive.

A weak order is *nontrivial* if for some a, b , $a \succsim b$ but not $b \succsim a$.

Axiom 2 (Continuity). For any $a, b, c \in \mathcal{S}$, the sets $\{\mu | \mu a \oplus (1 - \mu)b \succsim c\}$ and $\{\mu | c \succsim \mu a \oplus (1 - \mu)b\}$ are closed.

Axiom 3 (Independence). If $a, a', b \in \mathcal{S}$, $\mu \in (0, 1)$ then $a \succsim a' \Leftrightarrow \mu a \oplus (1 - \mu)b \succsim \mu a' \oplus (1 - \mu)b$.

Our independence axiom needs to be slightly stronger than that of Herstein and Milnor (1953). Reducibility allows them to generate our third axiom from a weaker assumption requiring only indifferences.

⁵In Section 4, we will see in more detail how the parameters affect decision times when T is arbitrary.

Example. In the context of our example, independence means that the decision duration of a decision process is increasing in the duration of every sub-decision process. In a process that can be written as $\mu a \oplus (1 - \mu)b$, the greater the decision time of a , the greater the decision time of $\mu a \oplus (1 - \mu)b$. Specifically, consider the comparison of decision times of the decision process between an airplane and a car and between a bus and a car. These only differ on the sub-decision process in case a car is not chosen. If the reaction time of the trivial decision process offering the airplane is just as long as the reaction time of being offered the bus, independence requires that also the decision process of the choice between an airplane and a car takes just as long as the decision process of a bus and a car. \square

Theorem 1. *Let \succsim be a binary relation on a procedural mixture set $\langle \mathcal{S}, \oplus, \sim \rangle$. Then the following two statements are equivalent.*

1. \succsim fulfills axioms 1-3.
2. \succsim is an entropy mixture value.

If U^1 and U^2 are entropy mixture value representations of the same nontrivial weak order, then $r^1 = r^2$, and if $r^1 = 1$, then $U^1 = \phi U^2 + \psi$ and $q^1 = \phi q^2$ and if $r^1 \neq 1$, then $U^1 = \phi U^2 + \psi$ and $q^1 = \phi q^2 + \psi$ where $\phi \in \mathbb{R}_+$ and $\psi \in \mathbb{R}$.

We have characterized two possible representations. Either we obtain the expected entropy mixture value of the mixed elements plus the Shannon (1948) entropy. Alternatively, we obtain the expected entropy mixture value under power-form probability distortions plus the Tsallis (1988) entropy. We delay the interpretation of the parameters of the model until discussing their comparative statics in Section 4. We first show that the characterization provides a theoretical foundation for the difficulty (see Ratcliff et al., 2016) of finding plausible extensions of the drift-diffusion model of decision times.

Example. It is noteworthy that we have only characterized a representation of the decision times and not the exact decision times. Thus, the actual decision times can be any increasing transformation of U . Therefore, the representation with $r = 1$, $q > 0$ and $U(x) = 0$ for trivial decision processes x is consistent with any model of *binary* decision processes in which the decision duration of $\mu x \oplus (1 - \mu)y$ is strictly increasing in $\min(\mu, 1 - \mu)$. This is the case for the drift-diffusion model of Ratcliff (1978). To obtain

the drift-diffusion model drift, the monotone transformation $T : \mathbb{R} \rightarrow \mathbb{R}$ would be

$$T = f \circ (H_1)^{-1} \quad (11)$$

$$f(\mu) = k \cdot \frac{1 - \mu - \mu}{\ln(1 - \mu) - \ln(\mu)} \quad (12)$$

$$(H_1)^{-1}(u) = \min\{\mu \in [0, 1] : H_1(\mu) = u\}. \quad (13)$$

In other words, T first recovers the probability $\mu \leq 1 - \mu$ from the entropy $H_1(\mu)$ and then applies the formula for the average decision time in a drift-diffusion model. This seems like forcing the issue but reveals the reason for the difficulty of finding extensions of the drift-diffusion model to multiple options: Suppose this extension fulfills Axioms 1-3 and agrees with the drift-diffusion model on binary choices. Since the decision times of choices among two and three alternatives overlap, the awkward form of T also applies to three-element choices and for such choices $(H_1)^{-1}$ does not recover a choice probability.

Extensions of the drift-diffusion model therefore face the following tradeoff: (1) they may give up on decision times of a process being continuously increasing in the decision times of sub-decision processes or (2) they may give up on choice probabilities fulfilling Luce's IIA axiom or (3) they accept the awkward form of T and try to find a stochastic process and boundary conditions that generate decision times that can be represented by an entropy. \square

Remark 1. The multi-mixture representations follow from compounding in a straightforward way, e.g.:

$$U \left(\alpha_1 a_1 \oplus (1 - \alpha_1) \left(\frac{\alpha_2}{1 - \alpha_1} a_2 \oplus \frac{1 - \alpha_1 - \alpha_2}{1 - \alpha_1} \left(\frac{\alpha_3}{1 - \alpha_1 - \alpha_2} a_3 \oplus \dots \right) \right) \right) \\ = \sum_i (\alpha_i)^r U(a_i) + q \cdot H_r(\alpha_1, \dots) \quad (14)$$

$$(15)$$

where the mixtures must be finite if $r \leq 1$ and

$$H_r(\alpha_1, \dots) \equiv \begin{cases} -\sum_i \alpha_i \ln \alpha_i, & r = 1 \\ \frac{1 - \sum_i (\alpha_i)^r}{r - 1}, & r \neq 1. \end{cases} \quad (16)$$

In many contexts, the Shannon (1948) measure is the standard measure of entropy. The use of the Shannon entropy in the previous representation entails the following property.

Axiom 4 (Mixture Cancellation). For all $a, a', b, b' \in \mathcal{S}$ and $\mu, \lambda \in (0, 1)$,

$$\begin{aligned} & (\mu + \lambda) \left(\frac{\mu}{\mu + \lambda} a \oplus \frac{\lambda}{\mu + \lambda} a' \right) \oplus (1 - \mu - \lambda) b \\ & \sim (\mu + \lambda) \left(\frac{\mu}{\mu + \lambda} a' \oplus \frac{\lambda}{\mu + \lambda} a \right) \oplus (1 - \mu - \lambda) b' \end{aligned} \quad (17)$$

$$\begin{aligned} & \Leftrightarrow (\mu + \lambda) a \oplus (1 - \mu - \lambda) b \\ & \sim (\mu + \lambda) a' \oplus (1 - \mu - \lambda) b'. \end{aligned} \quad (18)$$

It is straightforward to apply mixture cancellation to Theorem 1 to obtain the following corollary.

Corollary 1. Let \succsim be a binary relation on a procedural mixture set $\langle \mathcal{S}, \oplus, \sim \rangle$. Then the following two statements are equivalent.

1. \succsim fulfills axioms 1-4.
2. \succsim is an entropy mixture value with $r = 1$.

Example. In the context of decision processes mixture cancellation has a straightforward interpretation: Let a be a more difficult decision than a' and b' be more difficult than b exactly such that (18) holds. The decision processes in (17) can be understood as identical to the ones in (18) except that before⁶ the sub-decisions a and a' an additional decision with relative probability $\frac{\mu}{\mu + \lambda}$ is performed. The condition thus says that the different deliberation times of a and a' do not “interact” with the additional deliberation time from adding an additional decision. An example of such choices are given by the domain of choices that follow Hick’s law (Hick, 1952). Hick observed that with remarkable precision the response time to press a button in response to a signal increases logarithmically in the number of buttons, similar to how the Shannon entropy of uniform variables increases logarithmically in the number of outcomes. This suggests that $r = 1$ and T being the identity are suitable to model exact decision times for choices where Hick’s law applies.

However, this might not be the case if the decision makers become increasingly constrained in their decision making capability as the number of options increases. In this case, we would expect that if a takes longer

⁶By associativity, the additional decision could also be performed after a or a' .

than a' , then

$$\begin{aligned}
& (\mu + \lambda)a \oplus (1 - \mu - \lambda)b \\
& \sim (\mu + \lambda)a' \oplus (1 - \mu - \lambda)b' \\
\Rightarrow & \mu \left(\frac{\mu}{\mu + \lambda}a \oplus \frac{\lambda}{\mu + \lambda}a \right) \oplus (1 - \mu - \lambda)b \\
& \succ \mu \left(\frac{\mu}{\mu + \lambda}a' \oplus \frac{\lambda}{\mu + \lambda}a' \right) \oplus (1 - \mu - \lambda)b'. \tag{19}
\end{aligned}$$

That is, the additional decision with relative probability $\mu/(\mu + \lambda)$ interacts with the decision processes a and a' such that decision times increase more when this decision precedes the more complicated decision process a . As we will see in the comparative statics presented in Section 4, such behavior is closely linked to the parameter r . \square

We end this section with a corollary that applies the main theorem to stochastic choice models and that makes some of the informal discussion of the example application precise. Given the close link between Luce's IIA of decision probabilities and associativity, it is natural to simultaneously characterize the Luce model choice probabilities and entropy mixture decision times.

Let \mathcal{X} be a set of alternatives and \mathcal{C} be the set of finite subsets of \mathcal{X} . A stochastic choice function is a function $p : \mathcal{C} \times \mathcal{X} \rightarrow [0, 1]$ such that for all $C \in \mathcal{C}$, $x \notin C$, $p(x, C) = 0$ and $\sum_{x \in C} p(x, C) = 1$. For a more convenient notation, we often write $p_C(x) \equiv p(x, C)$. For any $C \subseteq D \in \mathcal{C}$, we further define $p_D(C) = \sum_{x \in C} p_D(x)$. A decision time $\tau : \mathcal{C} \rightarrow \mathbb{R}_+$ is a function that tells us for every finite subset of alternatives how long it takes (on average) to make a decision.

We introduce the following joint model⁷ of choice probabilities and decision times:

Definition 3 (Luce-Hick Model). A stochastic choice function p and a decision time τ form a Luce-Hick model if

1. there exists a function $v : \mathcal{X} \rightarrow \mathbb{R}$ such that for all $C \in \mathcal{C}$ and $x \in C$,

$$p_C(x) = \frac{\exp(v(x))}{\sum_{y \in C} \exp(v(y))}, \text{ and} \tag{20}$$

⁷This model differs from decision processes employed for example by Alós-Ferrer et al. (2021) because for each opportunity set only (average) decision times across all options are known instead of full probability distributions conditional on the chosen element.

2. there exists a continuous, strictly monotone function T and $r \in \mathbb{R}_{++}$ such that for all $C \in \mathcal{C}$,

$$T \circ \tau(C) = \begin{cases} \frac{1 - \sum_{x \in C} p_C(x)^r}{r-1} & r \neq 1 \\ \sum_{x \in C} -p_C(x) \ln p_C(x) & r = 1 \end{cases} \quad (21)$$

and $\tau(\{x\}) = \tau(\{y\}) = T^{-1}(0)$ for all $x, y \in \mathcal{X}$.

That is, in the Luce-Hick model the choice probabilities follow the Luce model of stochastic choice and a monotone transformation of the decision times (of equiprobable decisions) follows Hick's law. Compared with the empirical results of Hick (1952), the above definition makes the stronger claim that also the decision times of non-equiprobable decision processes can be represented by an entropy but neither requires T to be linear nor the entropy to be in Shannon form⁸, i.e., $r = 1$.

In order to characterize the Luce-Hick model via the procedural mixture set theorem, we require a sufficiently rich set of outcomes to generate decision processes with arbitrary choice probabilities.

Definition 4 (Richness of Outcomes). For every $x \in \mathcal{X}$ and every $\mu \in [0, 1]$ there exists a countably infinite number of alternatives $\{y_1, y_2, \dots\}$ such that $p_{\{x, y_i\}}(x) = \mu$.

We now introduce conditions that (given a rich set of alternatives) are necessary and sufficient to characterize the Luce-Hick model.

Definition 5 (Positivity). For all $x, y \in \mathcal{X}$, $p_{\{x, y\}}(x) > 0$ and $\tau(\{x, y\}) > \tau(\{x\})$.

Thus, every element of an opportunity set has a nonzero probability of being chosen and there is a positive deliberation time for the choice between at least two items.

Definition 6 (IIA). A stochastic choice function p fulfills IIA at $x, y \in \mathcal{X}$ if for all $C \in \mathcal{C}$ we have that

$$\frac{p_{\{x, y\}}(x)}{p_{\{x, y\}}(y)} = \frac{p_C(x)}{p_C(y)}. \quad (22)$$

⁸Interestingly, Pieron ('s 1952) law suggests reaction times in binary decisions to depend in power form on the stimulus intensity. In many experiments testing this hypothesis (Donkin & van Maanen, 2014), the stimulus is provided in the form of a mixing weight (e.g., the proportion of black and white dots as in Ratcliff and Rouder (1998)).

The stochastic choice function fulfills *IIA* if it fulfills *IIA* for all pairs of alternatives.

Luce's choice axiom states that relative probabilities are unaffected by the addition of other options. We next impose that comparative decision times are unaffected by additional options.

Definition 7 (Independent Decision Times). A stochastic choice function p and decision time τ fulfill independence of decision times if for all $C, D, E \in \mathcal{C}$ such that $(C \cup D) \cap E = \emptyset$ and $p_{C \cup E}(C) = p_{D \cup E}(D)$ it holds that

$$\begin{aligned} \tau(C) &\geq \tau(D) \\ \Leftrightarrow \quad \tau(C \cup E) &\geq \tau(D \cup E). \end{aligned} \tag{23}$$

This states that the decision time of a decision process is monotone in the decision time of its subprocesses, i.e., the time it would take to make a choice from a subset of the alternatives.

Definition 8 (Continuity of Decision Times). For all sequences of sets $\{A^k \equiv \{a_1^k, \dots, a_n^k\}\}_k$ and $A = \{a_1, \dots, a_m\}$, if $p_{A^k}(a_i^k) \rightarrow p_A(a_i)$ for all $i \in \{1, \dots, m\}$ and $p_{A^k}(a_i^k) \rightarrow 0$ for all $i \in \{m+1, \dots, n\}$ then $\tau(A^k) \rightarrow \tau(A)$.

Definition 9 (Sufficiency of Choice Probabilities).

Continuity has two main implications. First, it imposes that decision times are continuous in the choice probabilities of alternatives and only these choice probabilities matter for decision times. Second, it imposes that given a limit n on the number of alternatives, as choice probabilities of some $(m - n)$ many alternatives converge to zero, the mere presence of these alternatives does not affect the decision times.

The following corollary is now obvious:

Corollary 2 (Characterization of Luce-Hick Model). *Suppose \mathcal{X} fulfills richness in outcomes. Then the following statements are equivalent.*

1. p and τ fulfill positivity, *IIA*, independence of decision times, and continuity of decision times.
2. p and τ form a Luce-Hick model.

Interestingly, for very different reasons Luce was aware of the importance of his IIA axiom for the use of entropy in psychophysics, writing “[...] information theory implicitly presupposes the consequences of [IIA], which are relatively strong—specifically, when discrimination is imperfect, it means that choice behavior can be scaled by a ratio scale” Luce (1959, p.12).

4 COMPARATIVE STATICS

In the value of a procedural mixture, $U(\mu a \oplus (1 - \mu)b)$, the parameter q sets a threshold for $U(a)$ and $U(b)$ that determines whether mixing increases U or not. To make this precise, we introduce a positive and a negative value of mixing.

Definition 10 (Value of Mixing). \succsim exhibits a *negative (positive) value of mixing* at $a \in \mathcal{M}$ if $a \succ (\prec) \mu a \oplus (1 - \mu)a$.

The following result is then straightforward:

Proposition 1 (Monotone Mixing). *If \succsim has a mixture entropy representation, then the following statements are equivalent:*

1. \succsim exhibits a *negative (positive) value of mixing* at a ,
2. \succsim exhibits a *negative (positive) value of mixing* at $\mu a \oplus (1 - \mu)a$,
3. $U(a)(r - 1) > (<)q$.

From this result follows that if $r > 1$, then iteratively mixing an element with itself yields a sequence of elements for which U converges to $q/(r - 1)$. If $r \leq 1$, then U diverges to ∞ or $-\infty$, depending whether for the initial element $U(a)(r - 1) \gtrless q$.

Example. In our example data of Figure 1, the value of mixing is positive if T is an increasing function. If $r > 1$, then the mixture entropy U converges to q as the number of options increases. If $r \leq 1$, then additional options let U diverge to ∞ . It is noteworthy that this does not mean that decision times diverge. Since the representation is ordinal, the actual decision times $T \circ U$ may still be bounded in case $\lim_{u \rightarrow \infty} T(u) < \infty$. Thus, the limit behavior of decision times alone does not allow us to distinguish between $r < 1$ and $r > 1$. \square

In addition to setting a threshold for a positive value of mixing, q controls in a procedural mixture (e.g., $U(\mu a \oplus (1 - \mu)b)$) the relative importance of value derived from the mixture weight ($H_r(\alpha)$) compared with the value from the mixed elements ($U(a)$ and $U(b)$). The relevant comparative statics results are relegated to Appendix D because these results are only relevant if there are outcomes (i.e., elements that are not generated from mixtures themselves) $x \succ y$ as the following remark shows:

Remark 2. If \mathcal{S} is generated from finite procedural mixtures of members of a set \mathcal{X} and for all $x, y \in \mathcal{X}$, $U^1(x) = U^1(y)$, and $U^2(x) = U^2(y)$ then U^1 and U^2 represent the same relation if and only if the signs of $U^1(x)(r^1 - 1) - q^1$ and $U^1(x)(r^1 - 1) - q^1$ are identical and $r_1 = r_2$.

It follows from this remark that the magnitude of the parameter q only matters in comparison to a cardinal value of outcomes. If there do not exist outcomes $x \succ y$, then by the uniqueness properties of the representation we can find an affine transformation of U such that the valuation of any existing outcomes is equal to zero. Any subsequent multiplication of q by a positive factor results in an increasing linear transformation of U (which does not change the represented relation).

Example. The previous remark is the underlying reason why the Luce-Hick model only has a parameter r and no parameter q . It is plausible that trivial decisions always have the same reaction time and that nontrivial decisions take longer than trivial decisions. Thus, if $\mathcal{X} \ni x, y$ refers to the set of trivial decisions and $\tau(x) = \tau(y)$ for all its elements, then the only meaningful parameter is r . \square

We now turn to the interpretation of the parameter r . The parameter r controls the degree of the effect of mixing on the value. That is, it controls how much the value increases (or decreases) by an additional mixing stage.

Definition 11 (Comparative Value of Mixing). \succsim_1 yields a *higher value of mixing* than \succsim_2 if for all $\alpha, \beta, \gamma < 1/2$ and some $d \in \mathcal{S}$ at which \succsim_1 and \succsim_2 exhibit a positive value of mixing,

$$\alpha d \oplus (1 - \alpha)d \quad \succsim_1 \quad \beta(\gamma d \oplus (1 - \gamma)d) \oplus (1 - \beta)(\gamma d \oplus (1 - \gamma)d),$$

then

$$\alpha d \oplus (1 - \alpha)d \quad \succsim_2 \quad \beta(\gamma d \oplus (1 - \gamma)d) \oplus (1 - \beta)(\gamma d \oplus (1 - \gamma)d).$$

In words, if under \succsim_2 a binary mixture has a greater value than a mixture across four elements, then this must be also the case under \succsim_1 .

Proposition 2. *Let \succsim_1 and \succsim_2 be a mixture entropy value with representations U_1 and U_2 and parameters r_1, q_1 and r_2, q_2 , respectively. Then the following statements are equivalent.*

1. \succsim_1 yields a higher value of mixing than \succsim_2 .
2. $r_1 \geq r_2$.

Example. The decision data of Hick (1952) suggest that (given that T is linear), $r = 1$ is a plausible parameter for the decision of which one of a number of buttons on a keyboard to press. This suggests that the decision times of let's say whether to press a button with the left or right hand does not affect the additional decision time from choosing whether to press with the index finger or the pinkie. In contrast, preferential choices such as the snack choices commonly studied in experiments may become increasingly complex as the number of alternatives rises. Choices between food items may be relatively simple between two items but may become increasingly complex as additional options are added. Preferential choices would then exhibit a higher value of mixing, leading to a different parameter r . \square

5 DISJOINT INDEPENDENCE

The present section shows that a similar representation theorem as Theorem 1 holds for mixture sets when weakening the independence axiom instead of relaxing reducibility. Intuitively, procedural mixtures treat the mixture components as if they were distinct even when the mixed components are identical. We therefore restrict the independence axiom to hold only for distinct elements in order to obtain an analogous result on mixture sets. The main upside of this result is that it does not require the “mixture richness” of procedural mixture sets which require infinitely many distinct elements but this comes at the cost of notational elegance.

Example. The Luce model of stochastic choice is restrictive. In some cases, the associative structure generated by the Luce model only holds for a subset of the decisions. To show this, Figure 2 exemplifies the well-known red bus/blue bus paradox of Debreu (1960).

Option 1	Option 2	Option 3	Duration
AIRPLANE	BLUE BUS	CAR	1.9s
20%	20%	60 %	
AIRPLANE	BLUE BUS	-	1.5s
50%	50%		
BLUE BUS	RED BUS	CAR	1.4s
12.5%	12.5%	75%	
AIRPLANE	CAR	-	1.3s
25%	75%		
BLUE BUS	CAR	-	1.3s
25%	75%		
RED BUS	CAR	-	1.3s
25%	75%		
BLUE BUS	RED BUS	-	1.0s
50%	50%		
AIRPLANE	-	-	0.5s
100%			
RED BUS	-	-	0.5s
100%			

Figure 2: Choice Probabilities and Decision Time Data in Nested Stochastic Choice

The choice probabilities violate Luce's IIA axiom, because the relative choice probability of BLUE BUS and CAR depends on the presence of a RED BUS among the options: relative to the CAR, the choice of a BLUE BUS becomes less likely after a RED BUS is added to the options.

The decision time relation also violates independence because the decision between an AIRPLANE and a BLUE BUS takes longer than a decision between a BLUE BUS and a RED BUS, despite the singleton decisions for an AIRPLANE and for a RED BUS taking equally long.

However, such behavior is reasonable. If the decision maker does not care about the color of the bus, the decision between the red bus and the blue bus is trivial and may take less time than the more meaningful decision between an airplane and a bus. Therefore, in the upcoming

result we maintain that the independence axiom only holds for sufficiently distinct options. In the above example, both IIA and independence of decision times still hold among the three options AIRPLANE, BLUE BUS, and CAR but not among the options RED BUS, BLUE BUS, and CAR. \square

We introduce additional notation: Let \mathcal{Z} be a set. For a given mixture set \mathcal{M} , a *support* is a function $\text{supp} : \mathcal{M} \rightarrow \mathcal{Z}$ that fulfills for all $a, b \in \mathcal{M}$ and all $\alpha \in (0, 1)$: $\text{supp}(\alpha a \oplus (1 - \alpha)b) = \text{supp}(a) \cup \text{supp}(b)$. $\langle \mathcal{M}, \text{supp} \rangle$ is a *supported mixture set* if the image $\text{supp}(\mathcal{M})$ is closed under nonempty intersections and under nonempty relative complements. A subset Z of \mathcal{Z} is *essential* if there exist $a, b \in \mathcal{M}$ such that $\text{supp}(a) \subseteq \text{supp}(b) = Z$ and $a \not\sim b$.

Example. In the example, we may consider BLUE BUS and CAR to have disjoint support but BLUE BUS and RED BUS to not have disjoint support. This allows us to specify for which elements of the mixture set independence applies and for which it does not. \square

Axiom 5 (Disjoint Independence). For all $a, a', b \in \mathcal{M}$, $\mu \in (0, 1)$, if $(\text{supp}(a) \cup \text{supp}(a')) \cap \text{supp}(b) = \emptyset$ then

$$\begin{aligned} & a \succsim a' \\ \Leftrightarrow & \mu a \oplus (1 - \mu)b \succsim \mu a' \oplus (1 - \mu)b. \end{aligned} \quad (24)$$

We can embed a mixture set \mathcal{M} with a relation \succsim^* fulfilling Axioms 1, 2, and 5 partly into a procedural mixture set \mathcal{S} with a relation \succsim fulfilling Axioms 1-3. If there are sufficiently many essential subsets in the support, the embedded part has the same uniqueness properties as the mixture entropy representation and we obtain the following theorem:

Theorem 2 (Procedural Mixture Set Embedding). *Let $\langle \mathcal{M}, \text{supp} \rangle$ be a supported mixture set and \succsim^* be a binary relation on \mathcal{M} such that there exist at least three disjoint and essential subsets of \mathcal{X} .*

Then the following statements are equivalent:

1. *The relation \succsim^* fulfills Axioms 1, 2, and 5.*
2. *There exist parameters $q \in \mathbb{R}$, $r \in \mathbb{R}_{++}$, and a function $U : \mathcal{M} \rightarrow \mathbb{R}$ representing \succsim^* such that*

$$U(\mu a \oplus (1 - \mu)b) = \mu^r U(a) + (1 - \mu)^r U(b) + q \cdot H_r(\mu) \quad (25)$$

$$H_r(\mu) = \begin{cases} -\mu \ln \mu - (1 - \mu) \ln(1 - \mu), & r = 1 \\ \frac{1 - \mu^r - (1 - \mu)^r}{r - 1}, & r \neq 1 \end{cases} \quad (26)$$

if $\text{supp}(a) \cap \text{supp}(b) = \emptyset$. U is continuous in mixture weights.

Chen and Rommeswinkel (2020) prove a similar result for four disjoint subsets using a different proof technique.

we now combine Theorem 1 and Theorem 2 to characterize a model of decision times for nested stochastic choice (Kovach & Tserenjigmid, 2022). Concretely, we will characterize the following model:

Definition 12 (Nested Luce-Hick Model). A stochastic choice function p and a decision time τ form a *nested Luce-Hick model* if there exists a continuous function $v : \mathcal{C} \rightarrow \mathbb{R}_+$ with $v(C) = 0$ iff $C = \emptyset$, a unique parameter $r \in \mathbb{R}_{++}$, a unique strictly monotone continuous function $T : \tau(\mathcal{C}) \rightarrow \mathbb{R}$, a unique partition \mathcal{S} of \mathcal{X} , for all $S \in \mathcal{S}$ a unique set of parameters $r_S \in \mathbb{R}_{++}$, and strictly monotone continuous functions $t_S : \mathbb{R}_+ \rightarrow \mathbb{R}$ with $t_S(0) = 0$ which are unique up to joint linear transformations, such that for all sets $D \in \mathcal{C}$:

$$p_D(x) = \begin{cases} \frac{v(D \cap S)}{\sum_{S' \in \mathcal{S}} v(D \cap S')} \frac{v_S(x)}{\sum_{y \in S} v_S(y)}, & x \in D \\ 0, & \text{else,} \end{cases} \quad (27)$$

$$T(\tau(D)) = \sum_{S \in \mathcal{S}: S \cap D \neq \emptyset} p_D(S)^r \cdot t_S(H_{r_S}(p_{D \cap S}(x))) + H_r((p_D(S))_{S \in \mathcal{S}: p_D(S) > 0}). \quad (28)$$

Thus, for each category the decision maker has an entropy representation of the decision time contributions of choice within the category and the choice between categories also takes time according to an entropy representation. This model is highly flexible. It can capture that decision times across very different alternatives may take longer than choices between very similar alternatives or the reverse. It can also capture that within some but not necessarily all categories, choice becomes increasingly complex the more options are added or that choice within some category is much faster than in others.

Example. In Figure 2, the decision times are generated by a partition $\mathcal{S} = \{\{\text{AIRPLANE}\}, \{\text{BLUE BUS}, \text{RED BUS}\}, \{\text{CAR}\}\}$ $r = r_S = 1$, $T(t) = 0.5 + t/\ln 2$, $t_S(t) = t/2$ for all $S \in \mathcal{S}$. Effectively, the model treats the decision between categories the same way as the model in the introductory example. The decision within each category is however much faster, by a factor of 2. \square

As Kovach and Tserenjigmid (2022) show, the categories can be identified from whether IIA holds for pairs of options:

Definition 13 (Categorical Similarity). Two alternatives x and y are *categorically similar* if the stochastic choice function satisfies IIA at x, y . Alternatives x and y are *equally similar* to z if either both x and y are categorically similar to z or if neither x nor y are categorically similar to z .

Categorical similarity is an equivalence relation and therefore we can partition \mathcal{X} into sets of categorically similar alternatives. The nested stochastic choice rule that governs the decision probabilities fulfills the following axiom of Kovach and Tserenjigmid (2022).

Definition 14 (IIA for Equally Dissimilar Alternatives). Whenever x and y are equally similar to z , then for all sets A containing x, y :

$$\frac{p_A(x)}{p_A(y)} = \frac{p_{A \cup \{z\}}(x)}{p_{A \cup \{z\}}(y)}. \quad (29)$$

The following new axiom is the decision time counterpart to the previous axiom.

Definition 15 (Decision Time Independence for Equally Dissimilar Alternatives). Whenever all elements of C are equally dissimilar to all elements in $A \cup B$, and $p_{A \cup C}(A) = p_{B \cup C}(B)$ then:

$$\begin{aligned} \tau(A) &\geq \tau(B) \\ \Leftrightarrow \tau(A \cup C) &\geq \tau(B \cup C) \end{aligned} \quad (30)$$

Definition 16 (Category-wise Continuity of Decision Times). For all sequences of sets $\{A^k \equiv \{a_1^k, \dots, a_n^k\}\}_k$ and $A = \{a_1, \dots, a_m\}$, if for all $S \in \mathcal{S}$ $p(A^k \cap S) \rightarrow p(A \cap S)$ and $p_{A^k \cap S}(a_i^k) \rightarrow p_{A \cap S}(a_i)$ for all $i \in \{1, \dots, m\}$ and $p_{A^k \cap S}(a_i^k) \rightarrow 0$ for all $i \in \{m+1, \dots, n\}$ then $\tau(A^k) \rightarrow \tau(A)$.

In other words, if the choice probabilities of all categories converge and the choice probabilities within each category converge, then the decision time converges as well.

To generate a procedural mixture set within each category, we assume the following richness condition.

Definition 17 (Richness). For each $x \in \mathcal{X}$ and every $\alpha \in (0, 1)$ there exists a countably infinite number of categorically similar alternatives y and a categorically dissimilar alternative z such that $p_{\{x,y\}}(x) = \alpha = p_{\{x,z\}}(x)$.

Thus, in the nested logit we have an associative structure not only in the disjoint attribute case but also in the identical attribute case and can use Theorem 1 to embed a procedural mixture set to characterize decision times which may have different parameters r and q for different subsets of alternatives.

Corollary 3 (Characterization of Nested Luce-Hick Model). *Suppose p, τ has at least 3 equivalence classes of categorically similar alternatives and fulfills richness. Then the following statements are equivalent:*

1. p, τ is a nested Luce-Hick model.
2. p, τ fulfill positivity, category-wise continuity of decision times, IIA for equally dissimilar alternatives, and decision time independence for equally dissimilar alternatives.

6 LITERATURE

There are three branches of literature related to the present paper; a literature on axiomatic characterizations of entropies, a literature on axiomatic characterizations of decision times, and a literature on mixture sets and relaxations of the reduction of compound mixtures axiom.

6.1 CHARACTERIZATIONS OF ENTROPY FUNCTIONS

For a general survey of the literature of the characterization of information measures, see Csiszár (2008).

Krantz et al. (1971, ch. 3.12) defined entropy structures and showed that a relation represented by H_r fulfills the assumptions of an entropy structure. However, they did not provide a characterization result of H_r or H_1 . Their operation \circ of an entropy structure captures the idea of $a \circ b$ denoting the physical system consisting of two independent physical systems a and b . The mixture operation $\mu a \oplus (1 - \mu)b$ instead better applies to the mixture of distinguishable gases or liquids a and b with proportion μ and thus our representation captures the so-called *entropy of mixing*.

Closely related to the present paper is Luce et al. (2008b) in which the utility of gambling is characterized as expected utility plus the entropy of the lottery. There are three technical improvements the present paper

makes. First, Luce et al. (2008b) assume the existence of a status quo consequence and directly impose that the utility of a gamble between the status quo and some outcome occurring in some event is separable. Second, Luce et al. (2008b) assume that outcomes and gambles are closed under an operation they call “joint receipt”, interpreted as receiving two gambles simultaneously. They further assume that the utility over the two received gambles is additive, i.e., that the utility of the joint receipt of lotteries is the sum of the individual lotteries. Preferences over the gambles are therefore independent and thus the decision maker’s risk attitude over one gamble may not be influenced by whether the second gamble is risky or not. Third, Luce et al. (2008b) assume the existence of kernel equivalents. The kernel equivalent of a gamble is an outcome that when received simultaneously with an event-resolving but payoff-irrelevant gamble leaves the decision maker indifferent. Overall, their axioms are somewhat nonstandard and lack the accessibility of the mixture sets introduced in Herstein and Milnor (1953).

We show that only small adjustments to the standard axioms need to be made to obtain entropy measures as a utility component. We do not assume the joint receipt of gambles or the existence of a status quo outcome. Additive separability instead naturally arises from the von Neumann-Morgenstern independence axiom. While Luce et al. (2008b) assumes that certainty equivalents and kernel equivalents exist, our model and axiomatization are consistent with the nonexistence of certainty equivalents such as in the case when the mixture set is generated starting from mixtures of a finite set of alternatives, mixtures of these mixtures, etc..

The literature on rational inattention has provided characterizations of expected utility with entropy costs of attention (Caplin et al., 2017; de Oliveira et al., 2017). Ellis (2018), Lin (2020), and Lu (2016) characterize more general information cost functions. Most of this literature relies on observations of choices over menus or alternatives and treats choices over information structures as unknown.

6.2 DECISION PROCESSES AND AXIOMATIZATIONS OF RESPONSE TIMES

With respect to our application to decision processes, there exists a large literature on decision processes (Bogacz et al., 2006; Usher et al., 2013) especially the drift-diffusion model (Ratcliff, 1978; Ratcliff et al., 2016).

Several studies have proposed models for decision times in decision processes with multiple alternatives (Baldassi et al., 2020; Krajbich & Rangel, 2011; McMillen & Holmes, 2005; Tajima et al., 2019). Another interesting line of research are foundations for decision times when agents follow particular behavioral decision models. Most notably, this has been done for dual-process decision making (Achtziger & Alós-Ferrer, 2014; Alós-Ferrer, 2018), cognitive sophistication (Alós-Ferrer & Buckenmaier, 2025), rational inattention (Fudenberg et al., 2018), hyperbolic discounting (Chabris et al., 2009), and directed cognition (Gabaix et al., 2006). Most closely related to the present paper are the axiomatic studies discussed in more detail below.

Like the present paper, Baldassi et al. (2020) also employ the Luce model to characterize decision times. They obtain the decision times of the drift diffusion model for binary choice by imposing that across decisions the accuracy (in our notation $\max(\mu, 1 - \mu) - 1/2$) is proportional to the product of the average decision time multiplied by the ease of comparison $\ln(\max(\mu, 1 - \mu)) - \ln \min(\mu, 1 - \mu)$. This ad hoc functional imposition generates decision times as in the drift-diffusion model for binary choices. For multi-alternative choice, Baldassi et al. (2020) show that the Metropolis-DDM model (Cerreia-Vioglio et al., 2022), i.e., binary drift-diffusion comparisons together with Markovian exploration where choices are made at a fixed deadline, generates softmaximizing behavior.

Koida (2017) axiomatizes multiattribute decision times based on time-indexed preferences over lotteries of goods. Preferences at any point may be incomplete but become more and more decisive as time progresses and the decision maker resolves internal conflict over which attributes they care about. Decision times are interpreted as the moment at which the preference becomes decisive over two alternatives. Choices and their timing in the model are deterministic but predictions therefore naturally require the identification of a large number of parameters.

Fudenberg et al. (2020) characterize the binary drift-diffusion model as a joint probability distribution over decision times and the choice made from two options by imposing that the stopping time follows that of a Brownian motion and that the revealed boundary (as a function of the decision probability at any particular decision time, the average choice imbalance across time, and the average decision time) is nonnegative for all decision times.

Echenique and Saito (2017) axiomatize response times for binary choice data. Similar to the present study, they obtain a representation of response

times instead of a direct characterization of the functional form of response times. Different from the present study, they work with deterministic choices and distinguish between the response time to choose a over b and the response time to choose b over a . Most importantly, they address the issue of finite data while the present study requires a rich data set fulfilling (at least for a subset of the options) the IIA axiom.

6.3 MIXTURE SETS AND THE REDUCTION OF COMPOUND MIXTURES AXIOM

There is a vast literature of decision theoretic papers that employ the mixture sets introduced by Herstein and Milnor (1953). Commonly the axioms on preferences are being varied instead of the structure of the mixture set. In contrast, Mongin (2001) examines under which conditions mixture sets can be treated as convex subsets of a vector space.

The reduction of compound mixtures axiom has received substantial attention. The literature on recursive utility models following Kreps and Porteus (1978) analyzes intertemporal decision problems in which within each time period the reduction of compound mixtures axiom holds but between time periods it does not. A large literature following Segal (1990) remove the reduction of compound mixtures assumption completely and study two-period mixtures under various axioms on preferences. In contrast to their work, this paper studies mixtures with an arbitrary, finite number of stages and maintains that the order of resolution of compounding is irrelevant while the mixing itself is not.

7 CONCLUSION

The present analysis provides a foundation for the study of violations of betweenness due to procedural aspects. The entropy representation is obtained by relaxing the assumption that mixtures of an element with itself yields the same element or by weakening the independence axiom to mixtures of sufficiently distinct elements. Entropy measures play an important role in a large number of applications and the simple axiomatization provided in this paper may prove useful in other contexts.⁹

⁹For example, in the context of decisions under risk, uncertainty effects may induce violations of betweenness (Gneezy et al., 2006). This suggests that individuals may also attach a “procedural” value to the uncertainty of lotteries.

The application to decision processes provides a parsimonious model of the relation between choice probabilities and decision times. It is perhaps striking that the central prediction of the drift-diffusion model — that decision times are monotone in how even the choice probabilities are — is obtained from very simple assumptions about decision times for choices between multiple alternatives. However, the result can also be understood as an impossibility result; if one accepts that the decision time of a decision process should increase in the decision times of its subsets and the choice probabilities fulfill IIA, then one has to accept that decision times are related to choice probabilities in the somewhat restricted functional form of an entropy. While the representation is ordinally consistent with the binary drift-diffusion model, the very different functional form highlights the difficulty of extending the drift-diffusion model to multiple options.

By the example of nested stochastic choice we have shown that procedural mixtures and/or disjoint independence provides a starting point for characterizations in which the entropy represents decision times only on the domain of choices where the Luce model is plausible. There is much recent interest in the literature on axiomatic foundations of variations of the Luce model, e.g., the mixed logit (Saito, 2018), the nested logit (Kovach & Tserenjigmid, 2022), or the conditional logit (Breitmoser, 2020). Axiomatically studying decision times for such models would be an interesting avenue for future research given the prevalence of stochastic choice in empirical applications.

ACKNOWLEDGMENTS

This work was financially supported by the Center for Research in Econometric Theory and Applications (Grant No. 109-L900-203) from the Featured Areas Research Center Program within the framework of the Higher Education Sprout Project by the Ministry of Education (MOE) in Taiwan, and by the Ministry of Science and Technology (MOST), Taiwan, under Grant No. 107-2410-H-002-031 and 109-2634-F-002-045.

A PROOF OF THEOREM 1

Proof. Necessity is straightforward. We prove sufficiency.

Let $\mathcal{Q} = \mathcal{S} / \sim$ be the quotient set of \mathcal{S} with respect to the equivalence

relation \sim . Note that whenever $a, b \in \mathcal{S}$ and $a \sim b$, then any utility representation U must fulfill $U(a) = U(b)$. Note further that \mathcal{Q} is a procedural mixture set when endowed with \succsim^* such that $q \succsim^* r$ if and only if $a \succsim b$ for some $a \in q$ and $b \in r$. Thus, finding a utility on \mathcal{Q} is equivalent to finding a utility on \mathcal{S} . We therefore assume for the remainder of the proof that $\mathcal{S} = \mathcal{Q}$.

Let the order topology on \mathcal{S} be the topology generated by the subbase of upper and lower contour sets of the asymmetric part of \succsim .

Lemma 1. *\mathcal{S} is topologically connected under the order topology.*

Proof. If \mathcal{S} is not connected, then it is the union of two nonempty disjoint open sets \mathcal{S}' and \mathcal{S}'' . Take any elements $s' \in \mathcal{S}'$ and $s'' \in \mathcal{S}''$. The set $\mathcal{S}''' = \{a \mid \exists \mu : a = \mu s' \oplus (1 - \mu)s''\}$ is disconnected in the subspace topology by the disjoint nonempty open sets $\mathcal{S}' \cap \mathcal{S}'''$ and $\mathcal{S}'' \cap \mathcal{S}'''$. Since the upper and lower contour sets of \succsim form a subbase of \mathcal{S} , the upper and lower contour sets of \succsim in \mathcal{S}''' form a subbase of the subspace topology. By Axiom 2, the bijection $f : \mu \mapsto \mu s' \oplus (1 - \mu)s''$ is then continuous. But then the preimages $f^{-1}(\mathcal{S}' \cap \mathcal{S}''')$ and $f^{-1}(\mathcal{S}'' \cap \mathcal{S}''')$ are open, disjoint, and disconnect the unit interval, a contradiction. \square

Lemma 2. *\succsim is coseparable, i.e.,*

$$\mu a \oplus (1 - \mu)b \sim \bar{\mu} \bar{a} \oplus (1 - \bar{\mu}) \bar{b} \quad (31)$$

$$\mu a' \oplus (1 - \mu)b \sim \bar{\mu} \bar{a}' \oplus (1 - \bar{\mu}) \bar{b} \quad (32)$$

$$\mu a \oplus (1 - \mu)b' \sim \bar{\mu} \bar{a} \oplus (1 - \bar{\mu}) \bar{b}' \quad (33)$$

jointly imply

$$\mu a' \oplus (1 - \mu)b' \sim \bar{\mu} \bar{a}' \oplus (1 - \bar{\mu}) \bar{b}' \quad (34)$$

Proof. Using commutativity and associativity it is straightforward to show that

$$1/2[\mu a \oplus (1 - \mu)b] \oplus 1/2[\mu a' \oplus (1 - \mu)b'] \quad (35)$$

$$= 1/2[\mu a' \oplus (1 - \mu)b] \oplus 1/2[\mu a \oplus (1 - \mu)b'] \quad (36)$$

for any μ, a, b, a', b' . Using Axiom 3 together with the assumptions stated above then guarantee the desired result. \square

Lemma 3. *\succsim can be represented by continuous U, F such that*

$$U(\mu a \oplus (1 - \mu)b) = F(a, \mu) + F(b, 1 - \mu) \quad (37)$$

Proof. We either obtain the representation trivially, if $a \sim b$ for all $a, b \in \mathcal{S}$ or using the main theorem of Qin and Rommeswinkel (2024) which provides a representation theorem for weak orders on (open subsets of) $\mathcal{X} \times \mathcal{Y} \times \mathcal{Z}$ with the representation $f(x, z) + g(y, z)$. Here we choose $\mathcal{X} = \mathcal{S}$, $\mathcal{Y} = \mathcal{S}$, and $\mathcal{Z} = (0, 1)$ and endow the space with the product topology of the order topologies and the subspace topology of the reals. Thus, we will first obtain the representation on $\mu \in (0, 1)$ and then extend it to $[0, 1]$ using Axiom 2. To apply the main theorem of Qin and Rommeswinkel (2024), we require the following conditions: essentiality, conditional independence of the \mathcal{X} and \mathcal{Y} dimension given \mathcal{Z} , coseparability of \mathcal{X} and \mathcal{Y} given \mathcal{Z} , continuity in the product topology, and topological connectedness of \mathcal{X} , \mathcal{Y} , and \mathcal{Z} .

Since we have a product space, the well-behavedness assumptions of Qin and Rommeswinkel (2024) are not needed and we also only need essentiality instead of strict essentiality. Essentiality requires that for at least some μ and some a , then there exist some b, b' such that $\mu a \oplus (1 - \mu)b \not\sim \mu a \oplus (1 - \mu)b'$ and for some a, b there exist some μ, μ' such that $\mu a \oplus (1 - \mu)b \not\sim \mu' a \oplus (1 - \mu')b$. The former is guaranteed by Axiom 3 and the exclusion of the case $a \sim b$ for all $a, b \in \mathcal{S}$. The latter is guaranteed by Axiom 2 and the exclusion of the case $a \sim b$ for all $a, b \in \mathcal{S}$. Next, we need conditional independence of the \mathcal{X} and \mathcal{Y} dimensions for fixed \mathcal{Z} dimension. This holds by Axiom 3. Further, coseparability of the \mathcal{X} and \mathcal{Y} dimension given \mathcal{Z} has been shown above. Continuity of \succsim holds in the order topology on \mathcal{S} . However, we require continuity in the product topology on $\mathcal{S} \times \mathcal{S} \times (0, 1)$. By Axioms 2 and 3 the product topology is finer than the order topology on \mathcal{S} , guaranteeing continuity in the product topology. Topological connectedness of the product topology follows from the connectedness of its components \mathcal{X} , \mathcal{Y} , and \mathcal{Z} . The interval $(0, 1)$ is obviously connected and each component \mathcal{S} is connected in the order topology.

From Qin and Rommeswinkel (2024) then follows the existence of functions F and E such that \succsim can be represented by

$$U(\mu a \oplus (1 - \mu)b) = F(a, \mu) + E(b, \mu) \quad (38)$$

Commutativity of the mixture set guarantees that we can redefine E and F such that $E(b, \mu) = F(b, 1 - \mu)$. To see this, note that from $U(\mu a \oplus (1 - \mu)b) = U((1 - \mu)b \oplus \mu a)$ follows that $F(b, 1 - \mu) + E(a, 1 - \mu) = F(a, \mu) + E(b, \mu)$. Since this holds for all a , $E(b, \mu) = F(b, 1 - \mu) + E(a^*, 1 - \mu) - F(a^*, \mu)$ for some arbitrarily chosen a^* . Thus, $E(b, \mu) = F(b, 1 -$

$\mu) + f(\mu)$ where $f(\mu) \equiv E(a^*, 1 - \mu) - F(a^*, \mu)$. Substituting in the original representation, $U(\mu a \oplus (1 - \mu)b) = F(a, \mu) + F(b, 1 - \mu) + f(\mu)$. Redefining $\hat{F}(a, \mu) = F(a, \mu) + \begin{cases} f(\mu)/2 & \mu < 1/2 \\ f(1 - \mu)/2 & \mu \geq 1/2. \end{cases}$, it follows that $U(\mu a \oplus (1 - \mu)b) = \hat{F}(a, \mu) + \hat{F}(b, 1 - \mu)$. \square

Lemma 4. $F(a, \mu) = A(\mu)U(a) + B(\mu)$ for all μ and all $a \in \mathcal{S}$.

Proof. For fixed μ , $F(a, \mu)$ is a monotone transformation of U :

$$F(a, \mu) \geq F(b, \mu) \quad (39)$$

$$\Leftrightarrow F(a, \mu) + F(c, 1 - \mu) \geq F(b, \mu) + F(c, 1 - \mu) \quad (40)$$

$$\Leftrightarrow \mu a \oplus (1 - \mu)c \succsim \mu b \oplus (1 - \mu)c \quad (41)$$

$$\Leftrightarrow a \succsim b \quad (42)$$

$$\Leftrightarrow U(a) \geq U(b) \quad (43)$$

Therefore, we can write $F(a, \mu) = G(U(a), \mu)$. We obtain from associativity:

$$U(\mu a \oplus (1 - \mu)[\lambda b \oplus (1 - \lambda)c]) \quad (44)$$

$$= G(U(a), \mu) + G(G(U(b), \lambda) + G(U(c), 1 - \lambda), 1 - \mu) \quad (45)$$

$$= G(U(b), (1 - \mu)\lambda) + G(G(U(a), \frac{\mu}{1 - (1 - \mu)\lambda}) + G(U(c), \frac{(1 - \mu)(1 - \lambda)}{1 - (1 - \mu)\lambda}), 1 - (1 - \mu)\lambda) \quad (46)$$

$$= U((1 - \mu)\lambda b \oplus (1 - (1 - \mu)\lambda)[\frac{\mu}{1 - (1 - \mu)\lambda}a \oplus (1 - \lambda)\frac{(1 - \mu)(1 - \lambda)}{1 - (1 - \mu)\lambda}c]) \quad (47)$$

Noting that we have two continuous additive representations over $\mathcal{S} \times \mathcal{S}$ (specifically here the elements a and b), by the uniqueness of additive representations, we have that $G(\cdot, 1 - \mu)$ in (45) is positively affine in its first argument. Since b, c and μ, λ are arbitrary, this holds for all utility levels. Therefore $G(U(a), \mu) = A(\mu)U(a) + B(\mu)$ for all $a, b \in \mathcal{S}$ and $\mu \in [0, 1]$. \square

Lemma 5. $A(\mu) = \mu^r, r \in \mathbb{R}_{++}$.

Proof. We define $H(\mu) = H(1 - \mu) = B(\mu) + B(1 - \mu)$. Using associativity, we can derive that

$$A(\lambda) [A(\mu)U(a) + A(1 - \mu)U(b) + H(\mu)] + A(1 - \lambda)U(c) + H(\lambda) \quad (48)$$

$$\begin{aligned} &= A(\lambda\mu)U(a) + H(\lambda\mu) \\ &\quad + A(1 - \lambda\mu) \left[A\left(\frac{\lambda(1 - \mu)}{1 - \lambda\mu}\right)U(b) + A\left(\frac{1 - \lambda}{1 - \lambda\mu}\right)U(c) + H\left(\frac{\lambda(1 - \mu)}{1 - \lambda\mu}\right) \right] \end{aligned} \quad (49)$$

Consider a substitution a' for a under which the above condition needs to still hold. If $\Delta U = U(a) - U(a')$, then it follows that

$$A(\lambda)A(\mu)\Delta U = A(\lambda\mu)\Delta U \quad (50)$$

and therefore A is multiplicative. Using Cauchy's functional equation it is straightforward to derive that $A(\mu) = \mu^r$, $r \in \mathbb{R}$. By Axiom 3, $r > 0$. \square

We now finish the proof. We obtain

$$\lambda^r H(\mu) + H(\lambda) = (1 - \lambda\mu)^r \left[H\left(\frac{\lambda(1 - \mu)}{1 - \lambda\mu}\right) \right] + H(\lambda\mu) \quad (51)$$

and substitute: $\lambda = 1 - x$ and $\lambda\mu = y$. Using $H(x) = H(1 - x)$ we obtain:

$$(1 - x)^r H\left(\frac{y}{1 - x}\right) + H(x) = (1 - y)^r H\left(\frac{x}{1 - y}\right) + H(y) \quad (52)$$

with two types of solutions (Ebanks et al., 1987):

$$A(\mu) = \mu; \quad H(\mu) = -(\mu \ln \mu + (1 - \mu) \ln(1 - \mu))q + s \quad (53)$$

$$A(\mu) = \mu^r; \quad H(\mu) = -(\mu^r + (1 - \mu)^r - 1)q + s \quad (54)$$

where $q, s \in \mathbb{R}$. From Axiom 2 and connectedness, we also have that in both representations $s = 0$. We have therefore obtained the desired representation:

$$U(\mu a \oplus (1 - \mu)b) = \mu^r U(a) + (1 - \mu)^r U(b) + q \cdot H_r(\mu) \quad (55)$$

$$\text{with } H_r(\mu) = \begin{cases} -\mu \ln \mu - (1 - \mu) \ln(1 - \mu), & r = 1 \\ -\mu^r - (1 - \mu)^r + 1, & r \neq 1 \end{cases} \quad (56)$$

Regarding uniqueness, note that if preferences are nontrivial, then we immediately have an additively separable preference $U(\mu x \oplus (1 - \mu)y)$ over a continuum of x and y and thus U is unique up to affine transformations. The uniqueness properties of r and q follow immediately. \square

B PROOF OF COROLLARY 2

Proof. We prove sufficiency: The characterization of the Luce model is standard. We fix some $y \in \mathcal{X}$ and define $v(y) = 1$ and $v(x) = \ln p(x, \{x, y\}) - \ln 1 - p(x, \{x, y\})$. It is straightforward to then show that (20) holds.

We form an equivalence relation \approx on \mathcal{C} such that $\mathcal{C} \approx \mathcal{D}$ if and only if there exists enumerations $C = \{x_1, \dots, x_n\}$ and $D = \{y_1, \dots, y_n\}$ such that $p(x_i, C) = p(y_i, D)$ for all $i \in \{1, \dots, n\}$. From Continuity of Decision Times follows that if $C \approx D$, then $\tau(C) = \tau(D)$. Each element of \mathcal{C}/\approx can be represented by a finite tuple (μ_1, \dots, μ_n) with $\sum_i \mu_i = 1$, $\mu_i \in (0, 1]$, and the convention that $\mu_i \geq \mu_{i+1}$ for all $i \in \{0, \dots, n\}$. Notice that this makes a statement such as $C \in (\mu_1, \dots, \mu_n)$ meaningful; it means that the set C is an element of the equivalence class represented by (μ_1, \dots, μ_n) . We endow the set \mathcal{C}/\approx with an operation \oplus such that $\mu(\mu_1, \dots, \mu_n) \oplus (1 - \mu)(\lambda_1, \dots, \lambda_k)$ is the tuple obtained from rearranging $(\mu\mu_1, \dots, \mu\mu_n, (1 - \mu)\lambda_1, \dots, (1 - \mu)\lambda_k)$ into descending order. We further endow the mixture set $\langle \mathcal{C}/\approx, \oplus, = \rangle$ with the weak order induced by τ : $a \succsim b$ if there exist $C \in a$ and $D \in b$ such that $\tau(C) \geq \tau(D)$. By Continuity of Decision Times, indeed $a \succsim b$, $C \in a$ and $D \in b$ holds if and only if $\tau(C) \geq \tau(D)$.

Notice that if $C \cap E = \emptyset$, $p(C, C \cup E) = \mu$, $C \in a$, and $E \in b$, then $C \cup E \in \mu C \oplus (1 - \mu)E$. From independence of decision times then follows that the relation induced by τ on the procedural mixture set fulfills independence.

Continuity of \succsim follows straightforward from the fact that τ is continuous in the choice probabilities.

By Theorem 1 there exists a representation U of \succsim on \mathcal{C}/\approx . Since U is continuous and τ is continuous, there must exist a continuous monotone transformation T such that if $C \in b$, then $T \circ \tau(C) = U(b)$. Now let $C \cap D = \emptyset$, $C \in a$, $D \in b$ and $\mu = p(C, C \cup D)$. Then $T \circ \tau(C \cup D) = U(\mu a \oplus (1 - \mu)b) = p(C, C \cup D)^r T \circ \tau(C) + p(D, C \cup D)^r T \circ \tau(D) + q H_r(p(C, C \cup D))$. Since $\tau(\{x\}) = \tau(\{y\})$ for all x, y and U is unique up to affine transformations, we can assume without loss of generality that $U((1)) = 0$, i.e., $T \circ \tau(\{x\}) = 0$. If this is the case, then by Positivity and Remark 2 it is without loss of generality to assume $q = 1$. \square

C PROOF OF PROPOSITION 2

For notational convenience, we define $a \equiv \alpha d \oplus (1 - \alpha)d$ and $b = \beta c \oplus (1 - \beta)c$, where $c = \gamma d \oplus (1 - \gamma)d$.

$a \succ (\prec)d$ if and only if $\text{sgn}(q_1 - U_1(d)(r_1 - 1)) = \text{sgn}(q_2 - U_2(d)(r_2 - 1)) > (<)0$.

By the uniqueness properties of U , $a \succsim b$ if and only if

$$\text{sgn}(q - U(d)(r - 1))H_r(\alpha) \geq \text{sgn}(q - U(d)(r - 1))((\gamma^r + (1 - \gamma)^r)H_r(\beta) + H_r(\gamma)) \quad (57)$$

Thus, $a \succsim_1 b$ implies $a \succsim_2 b$ and $a \succ b_1$ implies $a \succ_2 b$ if one of the following is true: $q_1 - U_1(d)(r_1 - 1) = q_2 - U_2(d)(r_2 - 1) = 0$, $q_1 - U_1(d)(r_1 - 1) > 0 < q_2 - U_2(d)(r_2 - 1)$ and

$$\begin{aligned} H_{r_1}(\alpha) &\geq (>)(\gamma^{r_1} + (1 - \gamma)^{r_1})H_{r_1}(\beta) + H_{r_1}(\gamma) \\ \Rightarrow H_{r_2}(\alpha) &\geq (>)(\gamma^{r_2} + (1 - \gamma)^{r_2})H_{r_2}(\beta) + H_{r_2}(\gamma) \end{aligned} \quad (58)$$

or $q_1 - U_1(d)(r_1 - 1) < 0 < q_2 - U_2(d)(r_2 - 1)$ and (58) holds with opposite inequalities.

Define the Rényi (1961) entropy $R_r(\alpha) = \ln(\alpha^r + (1 - \alpha)^r)/(1 - r)$. Notice that $R_r(\alpha) \geq R_r(\beta)$ if and only if $H_r(\alpha) \geq H_r(\beta)$ and $H_r(\alpha) \geq (\gamma^r + (1 - \gamma)^r)H_r(\beta) + H_r(\gamma)$ if and only if $R_r(\alpha) \geq R_r(\beta) + R_r(\gamma)$. That is, the Rényi (1961) and Tsallis (1988) entropy are order-equivalent.

Lemma 6. Suppose $0 \leq r < s$, $\alpha, \beta, \gamma \leq 1/2$, and

$$R^r(\alpha) = R^r(\beta) + R^r(\gamma) \quad (59)$$

then,

$$R_s(\alpha) > R_s(\beta) + R_s(\gamma). \quad (60)$$

Proof. It is straightforward to show that $\alpha \geq \beta$ and $\alpha \geq \gamma$ since for $r > 0$, $R^r(\gamma) \geq 0$. We substitute: $x_1 = \alpha^{r-1}$, $x_2 = (1 - \alpha)^{r-1}$, $y_1 = (\beta\gamma)^{r-1}$, $y_2 = (\beta(1 - \gamma))^{r-1}$, $y_3 = ((1 - \beta)\gamma)^{r-1}$, $y_4 = ((1 - \beta)(1 - \gamma))^{r-1}$, $w_{ij} = (x_i y_j)^{1/(r-1)}$ and exponentiate both sides to obtain that (60) is equivalent to:

$$\text{sgn}(1 - s) \sum_{ij} w_{ij} (x_i^t - y_j^t) > 0 \quad (61)$$

where $t = (s - 1)/(r - 1)$.

Note that the vector y with weights $(w_{11} + w_{21}, \dots, w_{14} + w_{24})$ is a mean-preserving spread of the vector x with weights $(w_{11} + \dots + w_{14}, w_{21} + \dots + w_{24})$ since by (59), we have that

$$\sum_{ij} w_{ij}(x_i - y_j) = 0 \quad (62)$$

Since y is a mean-preserving spread of x , we have by the properties of generalized means that $M^t(\bar{w}, \bar{x}) \equiv (\sum_{ij} w_{ij} x_i^t)^{1/t} > (\sum_{ij} w_{ij} y_j^t)^{1/t} \equiv M^t(\bar{w}, \bar{y})$ if $t < 1$ and the reverse inequality holds if $t > 1$. It follows that $\sum_{ij} w_{ij}(x_i^t - y_j^t)$ is negative if $t > 1$ or $t < 0$ and positive if $0 < t < 1$. Since $0 < t < 1$ holds if and only if $s < 1$, (61) holds. \square

The lemma establishes that if at some r we have that (α, β, γ) are such that $a \sim_1 b$, then at a higher r it must be the case that $a \succ_2 b$. Since irrespective of the choice of s the LHS of (60) is increasing in $\alpha \leq 1$ and the RHS is increasing in $\beta \leq 1/2, \gamma \leq 1/2$, it follows that $\{(a, b) : a \succsim_1 b\} \subseteq \{(a, b) : a \succsim_2 b\}$

D FURTHER COMPARATIVE STATICS

The comparative statics of Section 4 focus with respect to the parameter q of the representation on the property whether $U(a)(r - 1) - q \gtrless 0$. The present section provides additional results that require the existence of nontrivial preference on a set of *consequences*, i.e. elements of \mathcal{S} that cannot be written in the form $\mu a \oplus (1 - \mu)b$ with $\mu \in (0, 1)$. Let \mathcal{X} be a set of consequences. The following definitions are the standard definitions of certainty equivalents and comparative risk aversion for mixture sets adjusted to the procedural mixture setting.

Definition 18 (Certainty Equivalent). The certainty equivalent $c = ce(\alpha x \oplus (1 - \alpha)y) \in \mathcal{X}$ of a procedural mixture of outcomes x and y is an outcome that fulfills $\alpha x \oplus (1 - \alpha)y \sim \alpha c \oplus (1 - \alpha)c$.

Definition 19 (Comparative Risk Aversion). \succsim_1 is at least as risk averse as \succsim_2 if for all $\alpha \in (0, 1)$ and all $x, y, z \in \mathcal{X}$, we have that

$$\alpha x \oplus (1 - \alpha)y \succsim_1 \alpha z \oplus (1 - \alpha)z \quad (63)$$

$$\Rightarrow \alpha x \oplus (1 - \alpha)y \succsim_2 \alpha z \oplus (1 - \alpha)z \quad (64)$$

Provided with our adjusted definitions, we can prove the following standard result for decisions under risk which extends to the procedural case:

Proposition 3. *Let \succsim_1 and \succsim_2 be mixture entropy values with representations U_1 and U_2 and parameters r_1, q_1 and r_2, q_2 , respectively. Let $U_1(\mathcal{X})$ and $U_2(\mathcal{X})$ be convex sets. Suppose there exist some $x, y \in \mathcal{X}$ such that $x \succ_1 y$. Then the following statements are equivalent.*

1. \succsim_1 is at least as risk averse as \succsim_2 .
2. The restriction of U_1 to \mathcal{X} is a concave monotone transformation of U_2 and $r_1 = r_2$.

Proof. \Leftarrow is trivial, we prove \Rightarrow : It is straightforward to show that for all $z, w \in \mathcal{X}$, $z \succ_1 w$ if and only if $z \succ_2 w$. Since $H_r(1) = 0$ and \succsim_1 and \succsim_2 are continuous, it follows that utilities over outcomes must be continuous monotone transformations of another, i.e., $U_1 = T \circ U_2$ when restricted to \mathcal{X} .

Since the values of outcomes are a convex set, for every $x, y \in \mathcal{X}$ such that $x \succ_2 y$ we can find z such that $z = ce_1(1/2x \oplus 1/2y)$. Notice that by the definition of a certainty equivalent we have $U_1(x)/2 + U_1(y)/2 = U_1(z)$. If T is not concave, then for some such x and y , $U_2(x) + U_2(y) = T^{-1}(U_1(x))/2 + T^{-1}(U_1(y))/2 < T^{-1}(U_1(z)) = U_2(z)$. But then $1/2x \oplus 1/2y \succsim_1 1/2z$ but $1/2x \oplus 1/2y \prec_2 1/2z \oplus 1/2z$, contradicting that \succsim_1 is at least as risk averse as \succsim_2 . We have thus established that T is concave.

Notice now that if $r_1 \neq r_2$, then $p_1(\alpha) \equiv \frac{\alpha^{r_1}}{\alpha^{r_1} + (1-\alpha)^{r_1}} \neq \frac{\alpha^{r_2}}{\alpha^{r_2} + (1-\alpha)^{r_2}} \equiv p_2(\alpha)$. Without loss of generality, assume that $p_1(\alpha) \geq p_2(\alpha)$ for $\alpha \geq 1/2$. Since T is monotone and continuous, it is differentiable almost everywhere. Without loss of generality, assume T is differentiable at $U_2(x)$ and $U_2(x) = U_1(x)$ and $\partial T(U_2(x))/\partial U = 1$. Then we can find outcomes $x' \succ x \succ x''$ such that $p_1(\alpha)T(U_2(x')) + (1 - p_1(\alpha))T(U_2(x'')) > U_2(x) > p_2(\alpha)U_2(x') + (1 - p_2(\alpha))U_2(x'')$ contradicting that \succsim_1 is at least as risk averse as \succsim_2 . \square

Mixture entropy values which are equally risk averse can be compared by how much the value of consequences is compared to the value of mixing.

Definition 20 (Comparative Consequentialism). \succsim_2 is at least as consequentialist than \succsim_1 if for all $\alpha \in (0, 1)$ and all $x, y \in \mathcal{X}$, we have that

$$\alpha x \oplus (1 - \alpha)x \succsim_2 y \quad (65)$$

$$\Rightarrow \alpha x \oplus (1 - \alpha)x \succsim_1 y \quad (66)$$

Proposition 4. Let \succsim_1 and \succsim_2 be equally risk averse mixture entropy values with representations U_1 and U_2 and parameters r_1, q_1 and r_2, q_2 , respectively. Let $U_1(\mathcal{X})$ and $U_2(\mathcal{X})$ be convex sets. Suppose there exist some $x, y \in \mathcal{X}$ such that $x \succ_1 y$. Then the following statements are equivalent.

1. \succsim_2 is at least as consequentialist as \succsim_1 .
2. There exist $s \in \mathbb{R}_{>0}$ and $t \in \mathbb{R}$ such that $U_2(x) = sU_1(x) + t$ for all $x \in \mathcal{X}$ and $sq_1 + t \geq q_2$.

Proof. \Leftarrow is trivial, we prove \Rightarrow : If \succsim_1 and \succsim_2 are equally risk averse, then $r_1 = r_2 = r$ and U_1 is an affine transformation of U_2 on outcomes. Assume for the moment that $U_1 = U_2$ on outcomes. Notice that since $H_r(\alpha) \geq 0$ for all r and all α , (65) holds if and only if $q_1 \geq q_2$. Since U_2 may be an affine transformation of U_1 on outcomes, by the uniqueness properties of U , the desired result follows. \square

This provides a link between the parameters of our representation and the intensity of the value of mixing relative to the value of consequences. Notice that this comparison is only meaningful when $r_1 = r_2$ and the value of consequences are cardinally comparable.

E PROOF OF THEOREM 2

Proof. The intuition for the result is simply that similar to a procedural mixture set, a mixture set in which independence only applies to disjoint mixtures allows for $a \sim^* b$ and $\mu a \oplus (1 - \mu)b \not\sim \mu a \oplus (1 - \mu)a = a$ (since a and a do not have disjoint support). The key difficulty is that the disjoint independence axiom might not apply to sufficiently many elements of the mixture set to restrict preferences to the desired representation.¹⁰

To prove the result, we first extend \succsim^* from $\Delta\mathcal{X}$ to a set $\Delta\mathcal{X}^\infty$ which is a mixture set generated from finite mixtures of countably many copies of

¹⁰For example, if there are only two outcomes, disjoint independence does not restrict preferences.

\mathcal{X} . The resulting relation is additively separable across the different copies of \mathcal{X} . $\Delta\mathcal{X}^\infty$ contains a subset that is isomorphic to a procedural mixture set and on which \succsim^* fulfills the vNM axioms. We thus have by Theorem 1 the desired representation on the procedural mixture set. Because disjoint mixtures in \mathcal{X} coincide with procedural mixtures in the procedural mixture set, the utility representation on $\Delta\mathcal{X}$ fulfills (25). The details of these steps follow below.

Let $\mathcal{X}^\infty = \sqcup_{i=0}^\infty \mathcal{X}$ be the disjoint union of countably many copies of \mathcal{X} . $x_i^k \in \mathcal{X}^\infty$ refers to the k th copy of $x_i \in \mathcal{X}$. Let $\Delta\mathcal{X}^\infty$ be the mixture set generated from \mathcal{X}^∞ . A generic element of $\Delta\mathcal{X}^\infty$ can therefore be represented by $m = \{(x_i^k, \mu_i^k), \dots, (x_j^l, \mu_j^l)\}$ such that $\sum_{i,k} \mu_i^k = 1$. Note that $\mathcal{M} \subset \Delta\mathcal{X}^\infty$.

Let \mathcal{J} be a partition of the support such that there are three elements that each contain an essential pair of outcomes. By standard results (Wakker, 1989, e.g.), our axioms¹¹ together with the existence of three essential pairs of outcomes with mutually disjoint support guarantees that there exists an additive representation $U(m) = \sum_J u((x_i^1, \mu_i^1)_{i \in J})$ on $\Delta\mathcal{X}$ such that each component is normalized to zero if $\sum_{i \in J} \mu_i^1 = 0$. We can uniquely extend the relation \succsim^* on \mathcal{M} to $\Delta\mathcal{X}^\infty$ by summation of the utilities obtaining a utility representation unique up to affine transformations of the form $\sum_k \sum_{J \in \mathcal{J}} u((x_i^k, \mu_i^k)_{i \in J})$.

Let \mathcal{P} be the closure of \mathcal{X} under an operator \oplus , i.e., the minimal set such that $\mathcal{X} \subset \mathcal{P}$ and for all $p, q \in \mathcal{P}$ and all $\mu \in [0, 1]$, we have that $\mu p \oplus (1 - \mu)q \in \mathcal{P}$. Similarly, let \approx be the minimal relation such that the procedural mixture axioms are fulfilled. Notice that the quotient set \mathcal{P}/\approx is also a procedural mixture set with $=$ being the equivalence relation.

A generic element of \mathcal{P}/\approx can be represented by a finite set $\{(x_1, \mu_1), \dots, (x_n, \mu_n)\}$ where all $x_i \in \mathcal{X}$ with $x_i = x_j$ permitted also for $i \neq j$. Thus, there is a natural mapping from \mathcal{P}/\approx into $\Delta\mathcal{X}^\infty$ which we denote $\phi : \mathcal{P}/\approx \rightarrow \Delta\mathcal{X}^\infty$.

Let \succsim be defined by $p \succsim q$ if $\phi(p) \succsim^* \phi(q)$. It is straightforward to see that \succsim fulfills Weak Order and Continuity. Independence follows from the fact that \succsim^* has an additively separable representation across different copies of \mathcal{X} contained in \mathcal{X}^∞ and fulfills disjoint independence.

It follows that \succsim^* on \mathcal{P}/\approx has an entropy adjusted expected utility representation $V : \mathcal{P}/\approx \rightarrow \mathbb{R}$. Notice that on $\phi(\mathcal{P}/\approx) \subset \Delta\mathcal{X}^\infty$ we have that $V \circ \phi^{-1}$ is additively separable across the partition of indexes J . It follows

¹¹Disjoint independence implies preference separability across disjoint subsets of the support. Continuity implies topological connectedness of each dimension.

that $V \circ \phi^{-1}$ is an affine transformation of U . The desired functional form of disjoint mixtures when U is restricted to $\Delta\mathcal{X}$ follows. \square

F PROOF OF COROLLARY 3

Proof. The functional form of the decision probabilities follows from Kovach and Tserenjigmid (2022), Theorem 1. Within each category $S \in \mathcal{S}$, Corollary 2 yields that the decision times can be represented by a Tsallis entropy H_{r_S} . From category-wise continuity and disjoint independence follows that the overall decision time takes the functional form $\tau(D) = f(\{H_{r_S}(p_{D \cap S})\}_{S \in \mathcal{S}}; \{p_D(S)\}_{S \in \mathcal{S}})$. Across categories, we can thus represent each set by a probability distribution over \mathcal{S} and the entropy value in each category. By our richness assumption and the probabilities following a nested Luce model, for any combination of values of the entropies $\{H_{r_S}(\cdot)\}$ and any arbitrary probability over \mathcal{S} we can indeed find a set D that generates these entropy values and probability over categories. Thus, we have a mixture set which we endow with the support $\text{supp}(D) = S \in \mathcal{S} | p_D(S \cap D) > 0$. It is straightforward to see that axiom 5 holds for this supported mixture set. Theorem 2 then yields the representation after defining $t_S(D) = T^{-1}(f(H_{r_S}(p_{D \cap S}), 0, \dots, 0; 1, 0, \dots, 0))$. \square

REFERENCES

- Achtziger, A., & Alós-Ferrer, C. (2014). Fast or rational? a response-times study of bayesian updating. *Management Science*, 60(4), 923–938.
- Alós-Ferrer, C. (2018). A dual-process diffusion model. *Journal of Behavioral Decision Making*, 31, 203–218.
- Alós-Ferrer, C., & Buckenmaier, J. (2025). Cognitive sophistication and deliberation times. *Experimental Economics*, 24(2), 558–592.
- Alós-Ferrer, C., Fehr, E., & Netzer, N. (2021). Time will tell: Recovering preferences when choices are noisy. *Journal of Political Economy*, 129(6), 1667–1945.
- Baldassi, C., Cerreia-Vioglio, S., Maccheroni, F., Marinacci, M., & Pirazzini, M. (2020). A behavioral characterization of the drift diffusion model and its multialternative extension for choice under time pressure. *Management Science*, 66(11), 5075–5093.

- Bogacz, R., Brown, E., Moehlis, J., Holmes, P., & Cohen, J. (2006). The physics of optimal decision making: A formal analysis of models of performance in two-alternative forced-choice tasks. *Psychological Review*, 113, 700–765.
- Breitmoser, Y. (2020). An axiomatic foundation of conditional logit. *Economic Theory*, 72, 245–261.
- Caplin, A., Dean, M., & Leahy, J. (2017, August). *Rationally Inattentive Behavior: Characterizing and Generalizing Shannon Entropy* (w23652). National Bureau of Economic Research. Cambridge, MA. <https://doi.org/10.3386/w23652>
- Cerreia-Vioglio, S., Maccheroni, F., Marinacci, M., & Rustichini, A. (2022). Multinomial logit processes and preference discovery: Inside and outside the black box. *The Review of Economic Studies*, 90(3), 1155–1194.
- Chabris, C., Laibson, D., Morris, C. L., Schuldt, J. P., & Taubinsky, D. (2009). The allocation of time in decision-making. *Journal of the European Economic Association*, 7(2), 628–637.
- Chen, T.-Y., & Rommeswinkel, H. (2020). Measuring Consumer Freedom.
- Chew, S. H. (1989). Axiomatic utility theories with the betweenness property. *Annals of operations Research*, 19(1), 273–298.
- Csiszár, I. (2008). Axiomatic Characterizations of Information Measures. *Entropy*, 10, 261–273.
- de Oliveira, H., Denti, T., Mihm, M., & Ozbek, K. (2017). Rationally Inattentive Preferences and Hidden Information Costs. *Theoretical Economics*, 12(2), 621–654.
- Debreu, G. (1960). Review of rd luce, individual choice behavior: A theoretical analysis. *American Economic Review*, 50, 186–188.
- Donkin, C., & van Maanen, L. (2014). Journal of mathematical psychology. *Pieron's law is not just an artifact of the response mechanism*, 62–63, 22–32.
- Ebanks, B. R., Kannappan, P., & Ng, C. T. (1987). Generalized fundamental equation of information of multiplicative type. *Aequationes Mathematicae*, 32(1), 19–31. <https://doi.org/10.1007/BF02311295>
- Echenique, F., & Saito, K. (2017). Response time and utility. *Journal of Economic Behavior and Organization*, 139, 49–59.
- Ellis, A. (2018). Foundations for optimal inattention. *Journal of Economic Theory*, 173, 56–94.
- Fishburn, P. C. (1982). *Foundations of expected utility*. Reidel.

- Frankel, D., & Volij, O. (2011). Measuring school segregation. *Journal of Economic Theory*, 146(1), 1–38.
- Fudenberg, D., Newey, W., Strack, P., & Strzalecki, T. (2020). Testing the drift-diffusion model. *Proceedings of the National Academy of Sciences*, 117(52), 33141–33148.
- Fudenberg, D., Strack, P., & Strzalecki, T. (2018). Speed, accuracy, and the optimal timing of choices. *American Economic Review*, 108(12), 3651–3684.
- Gabaix, X., Laibson, D., Moloche, G., & Weinberg, S. (2006). Costly information acquisition: Experimental analysis of a boundedly rational model. *American Economic Review*, 96, 1043–1068.
- Gneezy, U., List, J. A., & Wu, G. (2006). The Uncertainty Effect: When a Risky Prospect Is Valued Less Than Its Worst Possible Outcome. *Quarterly Journal of Economics*, 121(4), 27.
- Hennessy, D. A., & Lapan, H. (2007). When different market concentration indices agree. *Economics Letters*, 95(2), 234–240. <https://doi.org/10.1016/j.econlet.2006.10.011>
- Herfindahl, O. C. (1950). *Concentration in the Steel Industry*. University Microfilms.
- Herstein, I. N., & Milnor, J. (1953). An Axiomatic Approach to Measurable Utility. *Econometrica*, 21(2), 291–297. <https://doi.org/10.2307/1905540>
- Hick, W. (1952). On the rate of gain of information. *Quarterly Journal of Experimental Psychology*, 4(1), 11–26.
- Hirschman, A. O. (1980). *National power and the structure of foreign trade*. Univ of California Press.
- Koida, N. (2017). A multiattribute decision time theory. *Theory and Decision*, 83, 407–430.
- Kovach, M., & Tserenjigmid, G. (2022). Behavioral foundations of nested stochastic choice and nested logit. *Journal of Political Economy*, 130(9), 2411–2461.
- Krajbich, I., & Rangel, A. (2011). Multialternative drift-diffusion model predicts the relationship between visual fixations and choice in value-based decisions. *PNAS*, 108(33), 13852–13857.
- Krantz, D. H., Luce, R. D., Suppes, P., & Tversky, A. (1971). *Foundations of measurement volume 1: Additive and polynomial representations* (Vol. 1). Dover Publications.

- Kreps, D. M., & Porteus, E. L. (1978). Temporal Resolution of Uncertainty and Dynamic Choice Theory. *Econometrica*, 46(1), 185. <https://doi.org/10.2307/1913656>
- Lin, Y.-H. (2020). Stochastic Choice and Rational Inattention.
- Lu, J. (2016). Random Choice and Private Information. *Econometrica*, 84(6), 1983–2027.
- Luce, R. D. (1959). *Individual choice behavior: A theoretical analysis*. Wiley.
- Luce, R. D. (1986). *Response times: Their role in inferring elementary mental organization*. Oxford University Press.
- Luce, R. D., Ng, C. T., Marley, A. A. J., & Aczél, J. (2008a). Utility of gambling I: Entropy modified linear weighted utility. *Economic Theory*, 36(1), 1–33. <https://doi.org/10.1007/s00199-007-0260-5>
- Luce, R. D., Ng, C. T., Marley, A. A. J., & Aczél, J. (2008b). Utility of gambling II: Risk, paradoxes, and data. *Economic Theory*, 36(2), 165–187. <https://doi.org/10.1007/s00199-007-0259-y>
- McMillen, T., & Holmes, P. (2005). The dynamics of choice among multiple alternatives. *Journal of Mathematical Psychology*, 50(1), 30–57.
- Mongin, P. (2001). A note on mixture sets in decision theory. *Decisions in Economics and Finance*, 24(1), 59–69. <https://doi.org/10.1007/s102030170010>
- Nehring, K., & Puppe, C. (2009). Diversity. In *Handbook of Rational and Social Choice*. Oxford University Press.
- Pieron, H. (1952). *The sensations: Their functions, processes, and mechanisms*. Mueller.
- Qin, W.-z., & Rommeswinkel, H. (2024). Quasi-separable Preferences. *Theory and Decision*, 96, 555–595.
- Ratcliff, R. (1978). A theory of memory retrieval. *Psychological Review*, 85(2), 59–108.
- Ratcliff, R., Smith, P. L., Brown, S. D., & McKoon, G. (2016). Diffusion decision model: Current issues and history. *Trends in Cognitive Science*, 20(4), 260–281.
- Ratcliff, R., & Rouder, J. N. (1998). Modeling response times for two-choice decisions. *Psychological Science*, 9(5), 347–356.
- Rényi, A. (1961). On measures of information and entropy. *Proceedings of the Fourth Berkeley Symposium on Mathematics, Statistics and Probability 1960*, 547–561.
- Rieskamp, J., Bussemeyer, J. R., & Mellers, B. A. (2006). Extending the bounds of rationality: Evidence and theories of preferential choice. *Journal of Economic Literature*, 44, 631–661.

- Roe, R. M., Busemeyer, J. R., & Townsend, J. T. (2001). Multialternative decision field theory: A dynamic connectionist model of decision making. *Psychological Review*, 108(2), 370–392.
- Saito, K. (2018). *Axiomatization of the mixed logit model* [Available at <https://authors.library.caltech.edu/99361/>].
- Segal, U. (1990). Two-Stage Lotteries without the Reduction Axiom. *Econometrica*, 58(2), 349. <https://doi.org/10.2307/2938207>
- Shannon, C. E. (1948). A Mathematical Theory of Communication. *The Bell System Technical Journal*, 27(3), 379–423, 623–656.
- Shorrocks, A. F. (1980). The Class of Additively Decomposable Inequality Measures. *Econometrica*, 48(3), 613.
- Sims, C. A. (2003). Implications of rational inattention. *Journal of Monetary Economics*, 50(3), 665–690. [https://doi.org/10.1016/S0304-3932\(03\)00029-1](https://doi.org/10.1016/S0304-3932(03)00029-1)
- Suppes, P. (1996). The nature and measurement of freedom. *Social Choice and Welfare*, 13(2), 183–200.
- Tajima, S., Drugowitsch, J., Patel, N., & Pouget, A. (2019). Optimal policy for multi-alternative decisions. *Nature Neuroscience*, 22, 1503–1511.
- Theil, H. (1965). The Information Approach to Demand Analysis. *Econometrica*, 33(1), 67–87.
- Theil, H. (1967). *Economics and Information Theory*. North-Holland.
- Tsallis, C. (1988). Possible generalization of boltzmann-gibbs statistics. *Journal of Statistical Physics*, 52, 479–487.
- Usher, M., Tsetsos, K., Yu, E., & Lagnado, D. A. (Eds.). (2013). *Dynamics of decision making: From evidence accumulation to preference and belief*. Frontiers.
- von Neumann, J., & Morgenstern, O. (1944). *Theory of Games and Economic Behavior*. Princeton University Press.
- Wakker, P. P. (1989). *Additive representations of preferences: A new foundation of decision analysis* (Vol. 4). Springer Science & Business Media.